

# Periodic Homogenization For Elliptic Nonlocal Equations

(PIMS Workshop on Analysis of nonlinear PDEs and free boundary problems)

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# The Set-Up

Family of Oscillatory Nonlocal Equations:

$$\begin{cases} F(u^\varepsilon, \frac{x}{\varepsilon}) = 0 & \text{in } D \\ u^\varepsilon = g & \text{on } \mathbb{R}^n \setminus D \end{cases}$$

Translation Invariant Limit Nonlocal Equations

$$\begin{cases} \bar{F}(\bar{u}, x) = 0 & \text{in } D \\ \bar{u} = g & \text{on } \mathbb{R}^n \setminus D. \end{cases}$$

GOAL

Prove there is a **unique nonlocal operator**  $\bar{F}$  so that  $u^\varepsilon$  will be very close to  $\bar{u}$  as  $\varepsilon \rightarrow 0$ . (Homogenization takes place.)

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$$\begin{cases} F(u^\varepsilon, \frac{x}{\varepsilon}) = 0 & \text{in } D \\ u^\varepsilon = g & \text{on } \mathbb{R}^n \setminus D \end{cases}$$

$$F(u, \frac{x}{\varepsilon}) = \inf_{\alpha} \sup_{\beta} \left\{ f^{\alpha\beta}(\frac{x}{\varepsilon}) + \int_{\mathbb{R}^n} (u(x+y) + u(x-y) - 2u(x)) K^{\alpha\beta}(\frac{x}{\varepsilon}, y) dy \right\}.$$

(Think of a more familiar **2nd order** equation:

$$F(D^2 u, \frac{x}{\varepsilon}) = \inf_{\alpha} \sup_{\beta} \left\{ f^{\alpha\beta}(\frac{x}{\varepsilon}) + a_{ij}^{\alpha\beta}(\frac{x}{\varepsilon}) u_{x_i x_j}(x) \right\} )$$

# The Set-Up

## Periodic Nonlocal Operator $G$

for all  $z \in \mathbb{Z}^n$

$$G(u, x + z) = G(u(\cdot + z), x)$$

Our  $F$  will be periodic when  $f^{\alpha\beta}$  and  $K^{\alpha\beta}$  are periodic in  $x$ .

## Translation Invariant Nonlocal Operator $G$

$G$  is translation invariant if for any  $y \in \mathbb{R}^n$ ,

$$G(u, x + y) = G(u(\cdot + y), x).$$

# Main Theorem

## Theorem (S. '08; Homogenization of Nonlocal Equations)

If  $F$  is periodic and uniformly elliptic, plus technical assumptions, then there exists a **translation invariant** elliptic nonlocal operator  $\bar{F}$  with the same ellipticity as  $F$ , such that  $u^\varepsilon \rightarrow \bar{u}$  locally uniformly and  $\bar{u}$  is the unique solution of

$$\begin{cases} \bar{F}(\bar{u}, x) = 0 & \text{in } D \\ \bar{u} = g & \text{on } \mathbb{R}^n \setminus D. \end{cases}$$

## Interpretations and Applications

- Linear Case– Determine effective dynamics of Lévy Process in inhomogeneous media

$$f\left(\frac{x}{\varepsilon}\right) + \int_{\mathbb{R}^n} (u(x+y) + u(x-y) - 2u(x))K\left(\frac{x}{\varepsilon}, y\right)dy$$

- Optimal Control Case– Determine an effective optimal cost of control of Lévy Processes in inhomogeneous media

$$\inf_{\alpha} \left\{ f^{\alpha}\left(\frac{x}{\varepsilon}\right) + \int_{\mathbb{R}^n} (u(x+y) + u(x-y) - 2u(x))K^{\alpha}\left(\frac{x}{\varepsilon}, y\right)dy \right\}$$

- Two Player Game Case– Determine an effective value of a two player game of a Lévy Process in inhomogeneous media

$$\inf_{\alpha} \sup_{\beta} \left\{ f^{\alpha\beta}\left(\frac{x}{\varepsilon}\right) + \int_{\mathbb{R}^n} (u(x+y) + u(x-y) - 2u(x))K^{\alpha\beta}\left(\frac{x}{\varepsilon}, y\right)dy \right\}$$

# The Set-Up– Assumptions on $F$

## “Ellipticity”

$$\frac{\lambda}{|y|^{n+\sigma}} \leq K^{\alpha\beta}(x, y) \leq \frac{\Lambda}{|y|^{n+\sigma}}$$

## Scaling

$$K^{\alpha\beta}(x, \lambda y) = \lambda^{-n-\sigma} K^{\alpha\beta}(x, y).$$

## Symmetry

$$K^{\alpha\beta}(x, -y) = K^{\alpha\beta}(x, y)$$



# Recent Background– Nonlocal Elliptic Equations

## Existence/Uniqueness (Barles-Chasseigne-Imbert)

Given basic assumptions on  $K^{\alpha\beta}$  and  $f^{\alpha\beta}$ , there exist unique solutions to the Dirichlet Problems  $F(u^\varepsilon, x/\varepsilon) = 0$ ,  $\bar{F}(\bar{u}, x) = 0$ .

## Regularity (Silvestre, Caffarelli-Silvestre)

$u^\varepsilon$  are Hölder continuous, depending only on  $\lambda, \Lambda, \|f^{\alpha\beta}\|_\infty$ , dimension, and  $g$ . (In particular, continuous uniformly in  $\varepsilon$ .)

## Nonlocal Ellipticity (Caffarelli-Silvestre)

If  $u$  and  $v$  are  $C^{1,1}$  at a point,  $x$ , then

$$M^-(u - v)(x) \leq F(u, x) - F(v, x) \leq M^+(u - v)(x).$$

$$M^- u(x) = \inf_{\alpha\beta} \left\{ L^{\alpha\beta} u(x) \right\} \quad \text{and} \quad M^+ u(x) = \sup_{\alpha\beta} \left\{ L^{\alpha\beta} u(x) \right\}.$$

## Recent Background– 2nd Order Homogenization

### The “Corrector” Equation (Caffarelli-Souganidis-Wang)

For each matrix,  $Q$ , fixed,  $\bar{F}(Q)$  is the **unique** constant such that the solutions,  $v^\varepsilon$ , of

$$\begin{cases} F(Q + D^2 v^\varepsilon, \frac{x}{\varepsilon}) = \bar{F}(Q) & \text{in } B_1 \\ v^\varepsilon(x) = 0 & \text{on } \partial B_1, \end{cases}$$

satisfy the **decay property** as  $\varepsilon \rightarrow 0$ ,  $\|v^\varepsilon\|_\infty \rightarrow 0$ .

This generalizes the notion of the

### True Corrector Equation (Lions-Papanicolaou-Varadhan, 1st order HJE)

$\bar{F}(Q)$  is the unique constant such that there is a global periodic solution of

$$F(Q + D^2 v, y) = \bar{F}(Q) \text{ in } \mathbb{R}^n.$$

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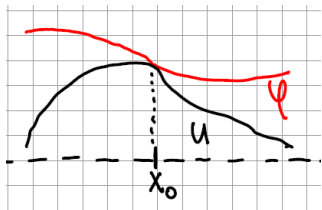
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# Perturbed Test Function Method

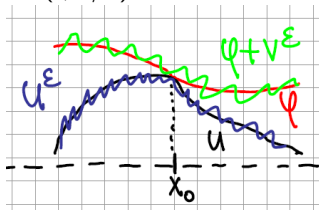
Need to Determine  
Effective operator

⇒

All information is in  
original operator  
 $F(\cdot, x/\varepsilon) = 0$



Can we **perturb**  
 $\phi$  to  $\phi + v^\varepsilon$   
to COMPARE  
WITH  $u^\varepsilon$ ???



$$\bar{F}(\phi, x_0) \geq 0$$

⇒

$$F(\phi + v^\varepsilon, x/\varepsilon) = \bar{F} \geq 0$$

To go BACK from comparison of  $\phi + v^\varepsilon$  and  $u^\varepsilon$   
TO comparison of  $\phi$  and  $u$  NEED

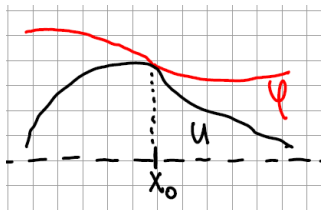
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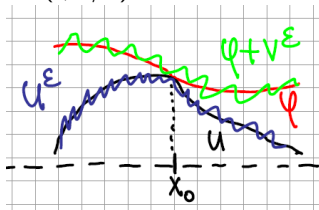
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# Strategy

- Most of the arguments for 2nd order homogenization are based on COMPARISON + REGULARITY
- Nonlocal equations have good COMPARISON + REGULARITY properties

⇒ We should try to modify techniques of the 2nd order setting to the nonlocal setting

## Difficulties Taking Ideas to Nonlocal Setting

- The space of test functions is much larger!  $C_b^2(\mathbb{R}^n)$  versus  $\mathcal{S}^n$
- Test function space is not invariant under the scaling of the operators  $u \mapsto \varepsilon^\sigma u(\cdot/\varepsilon)$
- $\bar{F}(\phi, \cdot)$  is a function, not a constant
- What should be the “corrector” equation? We can’t just “freeze” the hessian,  $D^2\phi(x_0)$ , at a point  $x_0$

# Scaling Test Functions?

## Bad Test Function Scaling, But Good $F$ Scaling

$$L^{\alpha\beta}[\varepsilon^\sigma u(\frac{\cdot}{\varepsilon})](x) = L^{\alpha\beta}[u](\frac{x}{\varepsilon})$$

$$L^{\alpha\beta}u(x) = \int_{\mathbb{R}^n} (u(x+y) + u(x-y) - 2u(x))K^{\alpha\beta}(\frac{x}{\varepsilon}, y)dy$$

## Put The Test Function Inside

$$\begin{cases} F(\phi + v^\varepsilon, \frac{x}{\varepsilon}) & = \mu \text{ in } B_1 \\ v^\varepsilon(x) & = 0 \text{ on } \mathbb{R}^n \setminus B_1, \end{cases}$$



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## “Corrector” Equation

equation for  $\phi + v^\varepsilon$

$$F(\phi + v^\varepsilon, \frac{x}{\varepsilon}) = \inf_{\alpha} \sup_{\beta} \left\{ f^{\alpha\beta}(\frac{x}{\varepsilon}) + \int_{\mathbb{R}^n} (\phi(x+y) + \phi(x-y) - 2\phi(x)) K^{\alpha\beta}(\frac{x}{\varepsilon}, y) dy + \int_{\mathbb{R}^n} (v^\varepsilon(x+y) + v^\varepsilon(x-y) - 2v^\varepsilon(x)) K^{\alpha\beta}(\frac{x}{\varepsilon}, y) dy \right\}$$

“frozen” operator on  $\phi$  at  $x_0$

$$[L^{\alpha\beta} \phi(x_0)](x) = \int_{\mathbb{R}^n} (\phi(x_0+z) + \phi(x_0-z) - 2\phi(x_0)) K^{\alpha\beta}(x, z) dz$$

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“frozen” operator on  $\phi$  at  $x_0$

$$[L^{\alpha\beta}\phi(x_0)](x) = \int_{\mathbb{R}^n} (\phi(x_0+z) + \phi(x_0-z) - 2\phi(x_0)) K^{\alpha\beta}(x, z) dz$$

# “Corrector” Equation

Analogy to 2nd order equation

$$a_{ij}\left(\frac{x}{\varepsilon}\right)(\phi + v)_{x_i x_j}(x) = a_{ij}\left(\frac{x}{\varepsilon}\right)\phi_{x_i x_j}(x) + a_{ij}\left(\frac{x}{\varepsilon}\right)v_{x_i x_j}(x)$$

and  $a_{ij}\left(\frac{x}{\varepsilon}\right)\phi_{x_i x_j}(x)$  is uniformly continuous in  $x$ .

Free and frozen variables,  $x$  and  $x_0$

Uniform continuity (Caffarelli-Silvestre)

$[L^{\alpha\beta}\phi(x_0)](x)$  is **uniformly continuous in  $x_0$** , independent of  $x$  and  $\alpha\beta$

## “Corrector” Equation

NEW OPERATOR  $F_{\phi, x_0}$

$$F_{\phi, x_0}(v^\varepsilon, \frac{x}{\varepsilon}) = \inf_{\alpha} \sup_{\beta} \left\{ f^{\alpha\beta}\left(\frac{x}{\varepsilon}\right) + [L^{\alpha\beta}\phi(x_0)]\left(\frac{x}{\varepsilon}\right) \right. \\ \left. + \int_{\mathbb{R}^n} (v^\varepsilon(x+y) + v^\varepsilon(x-y) - 2v^\varepsilon(x)) K^{\alpha\beta}\left(\frac{x}{\varepsilon}, y\right) dy \right\}$$

New “Corrector” Equation

$$\begin{cases} F_{\phi, x_0}(v^\varepsilon, \frac{x}{\varepsilon}) = \bar{F}(\phi, x_0) & \text{in } B_1(x_0) \\ v^\varepsilon = 0 & \text{on } \mathbb{R}^n \setminus B_1(x_0). \end{cases}$$

## “Corrector” Equation

### Proposition (S. '08; “Corrector” Equation)

There exists a **unique** choice for the value of  $\bar{F}(\phi, x_0)$  such that the solutions of the “corrector” equation also satisfy

$$\lim_{\varepsilon \rightarrow 0} \max_{B_1(x_0)} |v^\varepsilon| = 0.$$

(via the perturbed test function method, this proposition is equivalent to homogenization)

# Finding $\bar{F}$ ... Variational Problem

(Caffarelli-Souganidis-Wang... \*In spirit)

Consider a generic choice of a Right Hand Side,  $l$  is fixed

$$\begin{cases} F_{\phi, x_0}(v_j^\varepsilon, \frac{x}{\varepsilon}) = l & \text{in } B_1(x_0) \\ v_j^\varepsilon = 0 & \text{on } \mathbb{R}^n \setminus B_1(x_0). \end{cases}$$

How does the choice of  $l$  affect the decay of  $v_j^\varepsilon$ ?

decay property

$$\lim_{\varepsilon \rightarrow 0} \max_{B_1(x_0)} |v^\varepsilon| = 0 \iff (v_j^\varepsilon)^* = (v_j^\varepsilon)_* = 0$$

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Consider a generic choice of a Right Hand Side,  $l$  is fixed

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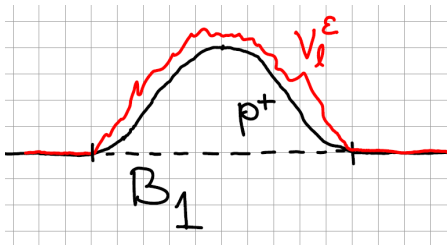
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# Variational Problem

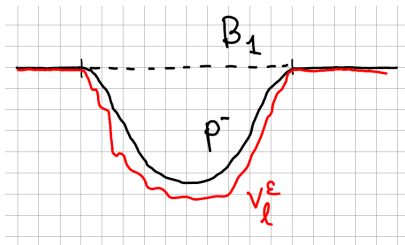
$l$  very negative

$p^+(x) = (1 - |x|^2)^2 \cdot \mathbb{1}_{B_1}$  is a **subsolution** of equation  
 $\implies (v_l^\varepsilon)_* > 0$  and we missed the goal.



$$\left( F_{\phi, x_0} \left( v_l^\varepsilon, \frac{x}{\varepsilon} \right) = l \right)$$

## Variational Problem



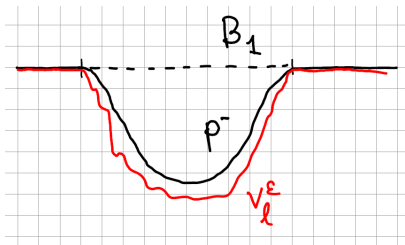
$$\left( F_{\phi, x_0}(v_l^\epsilon, \frac{x}{\epsilon}) = l \right)$$

$l$  very positive

$p^-(x) = -(|x|^2 - 1)^2 \cdot \mathbb{1}_{B_1}$  is a **supersolution** of equation  
 $\implies (v_l^\epsilon)^* < 0$  and we missed the goal, but in the other direction.

Can we choose an  $l$  in the middle that is "JUST RIGHT"?

## Variational Problem



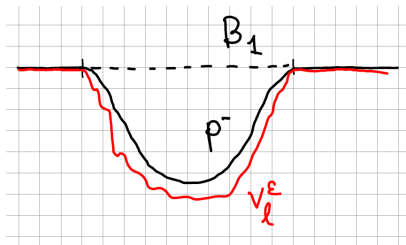
$$\left( F_{\phi, x_0}(v_l^\epsilon, \frac{x}{\epsilon}) = I \right)$$

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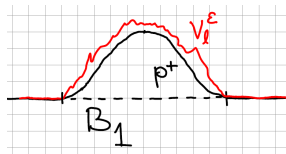
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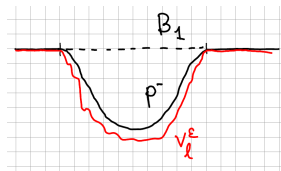
# Variational Problem



$$(I \ll 0)$$



$$I = ?????$$



$$(I \gg 0)$$

Can we choose an  $I$  in the middle that is “JUST RIGHT”?

# Obstacle Problem

(Caffarelli-Souganidis-Wang) The answer is YES.

## Information From Obstacle Problem

The obstacle problem gives relationship between the choice of  $l$  and the decay of  $v_l^\varepsilon$ .

# Obstacle Problem

## The Solution of The Obstacle Problem In a Set A

$$U_A^l = \inf \{ u : F_{\phi, x_0}(u, y) \leq l \text{ in } A \text{ and } u \geq 0 \text{ in } \mathbb{R}^n \}$$

**equation:**  $U_A^l$  is the least supersolution of  $F_{\phi, x_0} = l$  in  $A$

**obstacle:**  $U_A^l$  must be above the obstacle which is 0 in all of  $\mathbb{R}^n$

## Lemma (Hölder Continuity)

$U_A^l$  is  $\gamma$ -Hölder Continuous depending only on  $\lambda, \Lambda, \|f^{\alpha\beta}\|_{\infty}, \phi,$   
dimension, and  $A$ .

## Monotonicity and Periodicity of Obstacle Problem

If  $A \subset B$ , then  $U_A^l \leq U_B^l$ . For  $z \in \mathbb{Z}^n$ ,  $U_{A+z}^l(x) = U_A^l(x - z)$

# Obstacle Problem

## The Solution of The Obstacle Problem In a Set A

$$U_A^I = \inf \{ u : F_{\phi, x_0}(u, y) \leq I \text{ in } A \text{ and } u \geq 0 \text{ in } \mathbb{R}^n \}$$

**equation:**  $U_A^I$  is the least supersolution of  $F_{\phi, x_0} = I$  in  $A$

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# Obstacle Problem

## NOTATION

### Rescaled Solution

$$u^{\varepsilon, l} = \inf \left\{ u : F_{\phi, x_0} \left( u, \frac{y}{\varepsilon} \right) \leq l \text{ in } Q_1 \text{ and } u \geq 0 \text{ in } \mathbb{R}^n \right\}.$$

### Solution in $Q_1$ and Solution in $Q_{1/\varepsilon}$

$$u^{\varepsilon, l}(x) = \varepsilon^\sigma U_{Q_{1/\varepsilon}}^l \left( \frac{x}{\varepsilon} \right)$$

# Obstacle Problem

## Dichotomy

- (i) For all  $\varepsilon > 0$ ,  $U^l_{Q_{1/\varepsilon}} = 0$  for at least one point in **every** complete cell of  $\mathbb{Z}^n$  contained in  $Q_{1/\varepsilon}$ .
- (ii) There exists some  $\varepsilon_0$  and some cell,  $C_0$ , of  $\mathbb{Z}^n$  such that  $U^l_{Q_{1/\varepsilon_0}}(y) > 0$  for all  $y \in C_0$ .

Lemma (Part (i) of The Dichotomy)

*If (i) occurs, then  $(v_j^\varepsilon)^* \leq 0$ .*

Lemma (Part (ii) of The Dichotomy)

*If (ii) occurs, then  $(v_j^\varepsilon)_* \geq 0$*

# Obstacle Problem

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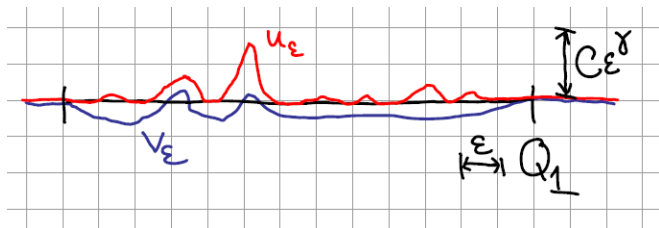
# Obstacle Problem

**Proof of First Lemma** (If (i) occurs, then  $(v_j^\varepsilon)^* \leq 0$ )...

- Rescale back to  $Q_1$ .

Definition of  $u^{\varepsilon,l} \implies v_j^\varepsilon \leq u^{\varepsilon,l}$

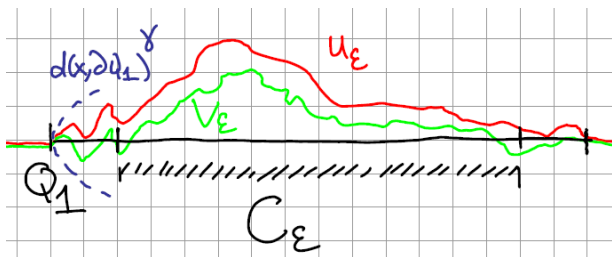
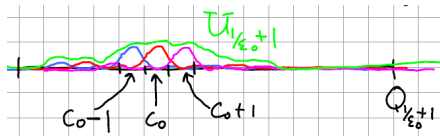
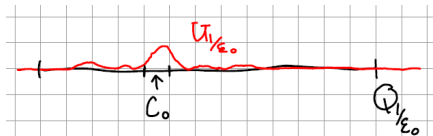
- (i)  $\implies u^{\varepsilon,l} = 0$  at least once in EVERY cell of  $\varepsilon\mathbb{Z}^n$ . Hölder Continuity  $\implies u^{\varepsilon,l} \leq C\varepsilon^\gamma$ .



## Obstacle Problem

**Proof of Second Lemma** (If (ii) occurs, then  $(v_l^\varepsilon)_* \geq 0$ )...

- Given any  $\delta > 0$ , Periodicity, Monotonicity, and (ii) allow construction of a **connected cube**  $C_\varepsilon \subset Q_1$  such that  $u^{\varepsilon,l} > 0$  in  $C_\varepsilon$  and  $|C_\varepsilon| / |Q_1| \geq 1 - \delta$ .



# Obstacle Problem

**Proof of Second Lemma continued** (If (ii) occurs, then  $(v_l^\varepsilon)_* \geq 0$ )

- Properties of  $u^{\varepsilon,l} \implies u^{\varepsilon,l}$  is a **solution** inside  $C_\varepsilon$ .
- Comparison with  $v_l^\varepsilon$  and boundary continuity  $\implies u^{\varepsilon,l} - v_l^\varepsilon \leq C(\delta^{1/n})^\gamma$ .
- Upper limit in  $\varepsilon$ :  $(-v_l^\varepsilon)^* \leq 0$
- Same as  $(v_l^\varepsilon)_* \geq 0$



## Choice for $\bar{F}$

Choose a special  $I$  such that  $I$  is ARBITRARILY CLOSE to values that give (i) **and** values that give (ii).

The Good Choice of  $\bar{F}$

$$\bar{F}(\phi, x_0) = \sup \left\{ I : (ii) \text{ happens for the family } (U'_{Q_{1/\varepsilon}})_{\varepsilon > 0} \right\}$$

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## Needed Properties for $\bar{F}$

Still need to show

### Elliptic Nonlocal Equation

- $\bar{F}(u, x)$  is well defined whenever  $u$  is bounded and “ $C^{1,1}$  at the point,  $x$ ”.
- $\bar{F}(u, \cdot)$  is a continuous function in an open set,  $\Omega$ , whenever  $u \in C^2(\Omega)$ .
- Ellipticity holds: If  $u$  and  $v$  are  $C^{1,1}$  at a point,  $x$ , then

$$M^-(u - v)(x) \leq \bar{F}(u, x) - \bar{F}(v, x) \leq M^+(u - v)(x).$$

### Comparison

This follows from ellipticity and translation invariance.

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# True Corrector Equation

## Periodic Corrector

$\bar{F}(\phi, x_0)$  is the unique constant such that the equation,

$$F_{\phi, x_0}(w, y) = \bar{F}(\phi, x_0) \text{ in } \mathbb{R}^n$$

admits a global periodic solution,  $w$ .

# Inf-Sup Formula

## Corollary: Inf-Sup formula

$$\bar{F}(\phi, x_0) = \inf_{\{W \text{ periodic}\}} \sup_{y \in \mathbb{R}^n} (F_{\phi, x_0}(W, y))$$

Thank You!