

# The continuous limit of large random planar maps

Jean-François Le Gall

Université Paris-Sud Orsay and Institut universitaire de France

Northwestern Probability Seminar, Redmond, October 2010

# Outline

**Goal:** To understand the **continuous limit** of large planar maps (planar maps are graphs drawn in the plane, or on the sphere) chosen **uniformly at random** in a certain class ( $p$ -angulations) viewed as **metric spaces** (for the graph distance)

- Expects **universality** of the limit
- Leads to an important continuous model (**Brownian map**)
- Gives insight into the properties of large planar maps.

Strong analogy with random paths and Brownian motion.

- 1 Introduction: planar maps
- 2 Bijections between maps and trees
- 3 Asymptotics for trees
- 4 The scaling limit of planar maps
- 5 Geodesics in the Brownian map

# Outline

**Goal:** To understand the **continuous limit** of large planar maps (planar maps are graphs drawn in the plane, or on the sphere) chosen **uniformly at random** in a certain class ( $p$ -angulations) viewed as **metric spaces** (for the graph distance)

- Expects **universality** of the limit
- Leads to an important continuous model (**Brownian map**)
- Gives insight into the properties of large planar maps.

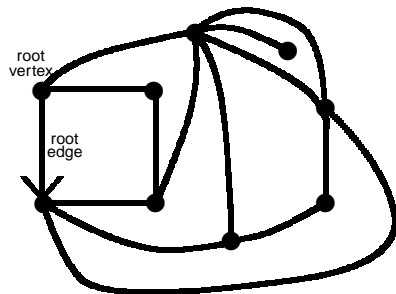
Strong analogy with random paths and Brownian motion.

- 1 Introduction: planar maps
- 2 Bijections between maps and trees
- 3 Asymptotics for trees
- 4 The scaling limit of planar maps
- 5 Geodesics in the Brownian map

# 1. Introduction: Planar maps

## Definition

A **planar map** is a proper embedding of a connected graph into the two-dimensional sphere (considered up to orientation-preserving homeomorphisms of the sphere).



A rooted quadrangulation

**Faces** = connected components of the complement of edges

*p*-angulation:

- each face has *p* adjacent edges

*p* = 3: triangulation

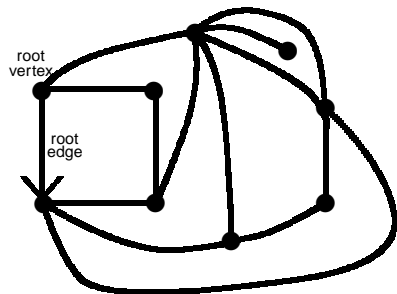
*p* = 4: quadrangulation

**Rooted map**: distinguished oriented edge

# 1. Introduction: Planar maps

## Definition

A **planar map** is a proper embedding of a connected graph into the two-dimensional sphere (considered up to orientation-preserving homeomorphisms of the sphere).



A rooted quadrangulation

**Faces** = connected components of the complement of edges

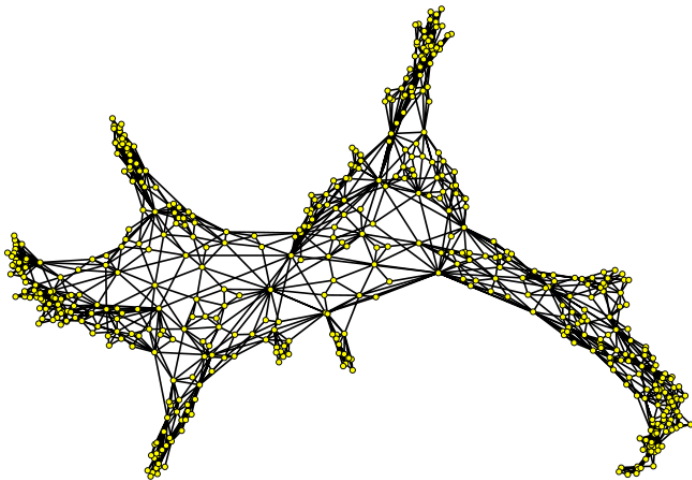
**$p$ -angulation:**

- each face has  $p$  adjacent edges

$p = 3$ : triangulation

$p = 4$ : quadrangulation

**Rooted map:** distinguished oriented edge



A large triangulation of the sphere (simulation by G. Schaeffer)  
Can we get a continuous model out of this ?

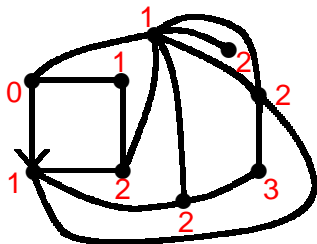
# What is meant by the continuous limit ?

$M$  planar map

- $V(M)$  = set of vertices of  $M$
- $d_{\text{gr}}$  **graph distance** on  $V(M)$
- $(V(M), d_{\text{gr}})$  is a (finite) **metric space**

$\mathbb{M}_n^p = \{\text{rooted } p\text{-angulations with } n \text{ faces}\}$   
(modulo deformations of the sphere)

$\mathbb{M}_n^p$  is a finite set



## Goal

Let  $M_n$  be chosen uniformly at random in  $\mathbb{M}_n^p$ . For some  $a > 0$ ,

$$(V(M_n), n^{-a} d_{\text{gr}}) \xrightarrow{n \rightarrow \infty} \text{“continuous limiting space”}$$

in the sense of the **Gromov-Hausdorff distance**.

## Remarks.

- Needs **rescaling** of the graph distance for a **compact** limit.
- It is believed that the limit does not depend on  $p$  (**universality**).

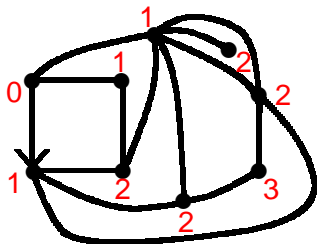
# What is meant by the continuous limit ?

$M$  planar map

- $V(M)$  = set of vertices of  $M$
- $d_{\text{gr}}$  **graph distance** on  $V(M)$
- $(V(M), d_{\text{gr}})$  is a (finite) **metric space**

$\mathbb{M}_n^p = \{\text{rooted } p\text{-angulations with } n \text{ faces}\}$   
(modulo deformations of the sphere)

$\mathbb{M}_n^p$  is a finite set



## Goal

Let  $M_n$  be chosen uniformly at random in  $\mathbb{M}_n^p$ . For some  $a > 0$ ,

$$(V(M_n), n^{-a} d_{\text{gr}}) \xrightarrow[n \rightarrow \infty]{} \text{“continuous limiting space”}$$

in the sense of the **Gromov-Hausdorff distance**.

## Remarks.

- Needs **rescaling** of the graph distance for a **compact** limit.
- It is believed that the limit does not depend on  $p$  (**universality**).



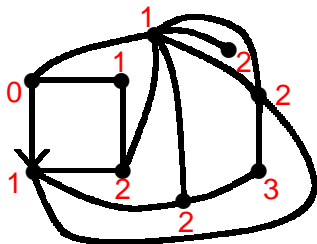
# What is meant by the continuous limit ?

$M$  planar map

- $V(M)$  = set of vertices of  $M$
- $d_{\text{gr}}$  **graph distance** on  $V(M)$
- $(V(M), d_{\text{gr}})$  is a (finite) **metric space**

$\mathbb{M}_n^p = \{\text{rooted } p\text{-angulations with } n \text{ faces}\}$   
(modulo deformations of the sphere)

$\mathbb{M}_n^p$  is a finite set



## Goal

Let  $M_n$  be chosen uniformly at random in  $\mathbb{M}_n^p$ . For some  $a > 0$ ,

$$(V(M_n), n^{-a} d_{\text{gr}}) \xrightarrow[n \rightarrow \infty]{} \text{“continuous limiting space”}$$

in the sense of the **Gromov-Hausdorff distance**.

## Remarks.

- Needs **rescaling** of the graph distance for a **compact** limit.
- It is believed that the limit does not depend on  $p$  (**universality**).

# The Gromov-Hausdorff distance

**The Hausdorff distance.**  $K_1, K_2$  compact subsets of a metric space

$$d_{\text{Haus}}(K_1, K_2) = \inf\{\varepsilon > 0 : K_1 \subset U_\varepsilon(K_2) \text{ and } K_2 \subset U_\varepsilon(K_1)\}$$

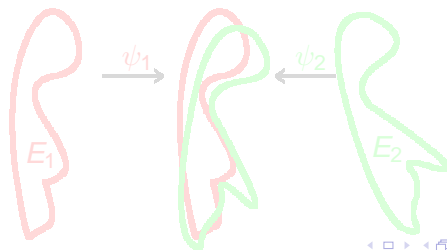
( $U_\varepsilon(K_1)$  is the  $\varepsilon$ -enlargement of  $K_1$ )

## Definition (Gromov-Hausdorff distance)

If  $(E_1, d_1)$  and  $(E_2, d_2)$  are two compact metric spaces,

$$d_{\text{GH}}(E_1, E_2) = \inf\{d_{\text{Haus}}(\psi_1(E_1), \psi_2(E_2))\}$$

the infimum is over all **isometric** embeddings  $\psi_1 : E_1 \rightarrow E$  and  $\psi_2 : E_2 \rightarrow E$  of  $E_1$  and  $E_2$  into the same metric space  $E$ .



# The Gromov-Hausdorff distance

**The Hausdorff distance.**  $K_1, K_2$  compact subsets of a metric space

$$d_{\text{Haus}}(K_1, K_2) = \inf\{\varepsilon > 0 : K_1 \subset U_\varepsilon(K_2) \text{ and } K_2 \subset U_\varepsilon(K_1)\}$$

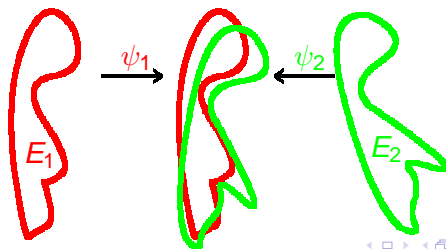
( $U_\varepsilon(K_1)$  is the  $\varepsilon$ -enlargement of  $K_1$ )

## Definition (Gromov-Hausdorff distance)

If  $(E_1, d_1)$  and  $(E_2, d_2)$  are two compact metric spaces,

$$d_{\text{GH}}(E_1, E_2) = \inf\{d_{\text{Haus}}(\psi_1(E_1), \psi_2(E_2))\}$$

the infimum is over all **isometric** embeddings  $\psi_1 : E_1 \rightarrow E$  and  $\psi_2 : E_2 \rightarrow E$  of  $E_1$  and  $E_2$  into the same metric space  $E$ .



# Gromov-Hausdorff convergence of rescaled maps

## Fact

If  $\mathbb{K} = \{\text{isometry classes of compact metric spaces}\}$ , then

$(\mathbb{K}, d_{\text{GH}})$  is a separable complete metric space (Polish space)

→ It makes sense to study the **convergence** of

$$(V(M_n), n^{-a}d_{\text{gr}})$$

as **random variables** with values in  $\mathbb{K}$ .

(Problem stated for triangulations by O. Schramm [ICM06])

**Choice of  $a$ .** The parameter  $a$  is chosen so that  $\text{diam}(V(M_n)) \approx n^a$ .

⇒  $a = \frac{1}{4}$  [cf Chassaing-Schaeffer PTRF 2004 for quadrangulations]

# Gromov-Hausdorff convergence of rescaled maps

## Fact

If  $\mathbb{K} = \{\text{isometry classes of compact metric spaces}\}$ , then

$(\mathbb{K}, d_{\text{GH}})$  is a separable complete metric space (Polish space)

→ It makes sense to study the **convergence** of

$$(V(M_n), n^{-a}d_{\text{gr}})$$

as **random variables** with values in  $\mathbb{K}$ .

(Problem stated for triangulations by O. Schramm [ICM06])

**Choice of  $a$ .** The parameter  $a$  is chosen so that  $\text{diam}(V(M_n)) \approx n^a$ .

⇒  **$a = \frac{1}{4}$**  [cf Chassaing-Schaeffer PTRF 2004 for quadrangulations]

# Why study planar maps and their continuous limits ?

- **combinatorics** [Tutte '60, four color theorem, etc.]
- **theoretical physics**
  - ▶ enumeration of maps related to matrix integrals [t Hooft 74, Brézin, Itzykson, Parisi, Zuber 78, etc.]
  - ▶ large random planar maps as models of random geometry (quantum gravity, cf Ambjørn, Durhuus, Jonsson 95, Duplantier-Sheffield 08)
- **probability theory**: models for a Brownian surface
  - ▶ analogy with Brownian motion as continuous limit of discrete paths
  - ▶ universality of the limit (conjectured by physicists)
- **metric geometry**: examples of singular metric spaces
- **algebraic and geometric motivations**: cf Lando-Zvonkin 04 *Graphs on surfaces and their applications*

# Why study planar maps and their continuous limits ?

- **combinatorics** [Tutte '60, four color theorem, etc.]
- **theoretical physics**
  - ▶ enumeration of maps related to matrix integrals [t Hooft 74, Brézin, Itzykson, Parisi, Zuber 78, etc.]
  - ▶ large random planar maps as models of random geometry (quantum gravity, cf Ambjørn, Durhuus, Jonsson 95, Duplantier-Sheffield 08)
- **probability theory**: models for a Brownian surface
  - ▶ analogy with Brownian motion as continuous limit of discrete paths
  - ▶ universality of the limit (conjectured by physicists)
- **metric geometry**: examples of singular metric spaces
- **algebraic and geometric motivations**: cf Lando-Zvonkin 04 *Graphs on surfaces and their applications*

# Why study planar maps and their continuous limits ?

- **combinatorics** [Tutte '60, four color theorem, etc.]
- **theoretical physics**
  - ▶ enumeration of maps related to matrix integrals [t Hooft 74, Brézin, Itzykson, Parisi, Zuber 78, etc.]
  - ▶ large random planar maps as models of random geometry (quantum gravity, cf Ambjørn, Durhuus, Jonsson 95, Duplantier-Sheffield 08)
- **probability theory**: models for a Brownian surface
  - ▶ analogy with Brownian motion as continuous limit of discrete paths
  - ▶ universality of the limit (conjectured by physicists)
- **metric geometry**: examples of singular metric spaces
- **algebraic and geometric motivations**: cf Lando-Zvonkin 04 *Graphs on surfaces and their applications*



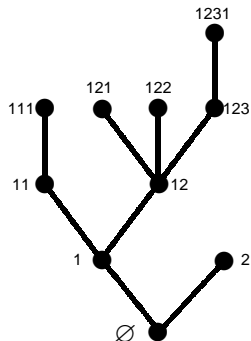
# Why study planar maps and their continuous limits ?

- **combinatorics** [Tutte '60, four color theorem, etc.]
- **theoretical physics**
  - ▶ enumeration of maps related to matrix integrals [t Hooft 74, Brézin, Itzykson, Parisi, Zuber 78, etc.]
  - ▶ large random planar maps as models of random geometry (quantum gravity, cf Ambjørn, Durhuus, Jonsson 95, Duplantier-Sheffield 08)
- **probability theory**: models for a Brownian surface
  - ▶ analogy with Brownian motion as continuous limit of discrete paths
  - ▶ universality of the limit (conjectured by physicists)
- **metric geometry**: examples of singular metric spaces
- **algebraic and geometric motivations**: cf Lando-Zvonkin 04 *Graphs on surfaces and their applications*

# Why study planar maps and their continuous limits ?

- **combinatorics** [Tutte '60, four color theorem, etc.]
- **theoretical physics**
  - ▶ enumeration of maps related to matrix integrals [t Hooft 74, Brézin, Itzykson, Parisi, Zuber 78, etc.]
  - ▶ large random planar maps as models of random geometry (quantum gravity, cf Ambjørn, Durhuus, Jonsson 95, Duplantier-Sheffield 08)
- **probability theory**: models for a Brownian surface
  - ▶ analogy with Brownian motion as continuous limit of discrete paths
  - ▶ universality of the limit (conjectured by physicists)
- **metric geometry**: examples of singular metric spaces
- **algebraic and geometric motivations**: cf Lando-Zvonkin 04 *Graphs on surfaces and their applications*

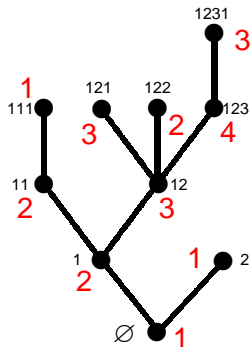
## 2. Bijections between maps and trees



A **planar tree**  $\tau = \{\emptyset, 1, 2, 11, \dots\}$

(rooted ordered tree)

the lexicographical order on vertices will play an important role in what follows



A **well-labeled tree**  $(\tau, (\ell_v)_{v \in \tau})$

Properties of labels:

- $\ell_{\emptyset} = 1$
- $\ell_v \in \{1, 2, 3, \dots\}, \forall v$
- $|\ell_v - \ell_{v'}| \leq 1$ , if  $v, v'$  neighbors

# Coding maps with trees, the case of quadrangulations

$\mathbb{T}_n = \{\text{well-labeled trees with } n \text{ edges}\}$

$\mathbb{M}_n^4 = \{\text{rooted quadrangulations with } n \text{ faces}\}$

## Theorem (Cori-Vauquelin, Schaeffer)

*There is a bijection  $\Phi : \mathbb{T}_n \longrightarrow \mathbb{M}_n^4$  such that, if  $M = \Phi(\tau, (\ell_v)_{v \in \tau})$ , then*

$$V(M) = \tau \cup \{\partial\} \quad (\partial \text{ is the root vertex of } M)$$

$$d_{\text{gr}}(\partial, v) = \ell_v, \forall v \in \tau$$

## Key facts.

- Vertices of  $\tau$  become vertices of  $M$
- The **label** in the tree becomes the **distance** from the root in the map.

Coding of **more general maps**: Bouttier, Di Francesco, Guitter (2004)

# Coding maps with trees, the case of quadrangulations

$\mathbb{T}_n = \{\text{well-labeled trees with } n \text{ edges}\}$

$\mathbb{M}_n^4 = \{\text{rooted quadrangulations with } n \text{ faces}\}$

## Theorem (Cori-Vauquelin, Schaeffer)

*There is a bijection  $\Phi : \mathbb{T}_n \longrightarrow \mathbb{M}_n^4$  such that, if  $M = \Phi(\tau, (\ell_v)_{v \in \tau})$ , then*

$$V(M) = \tau \cup \{\partial\} \quad (\partial \text{ is the root vertex of } M)$$

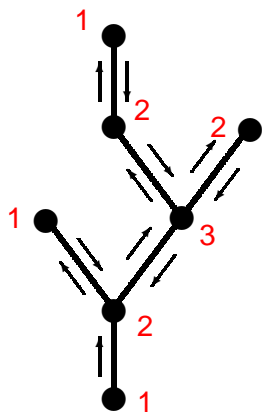
$$d_{\text{gr}}(\partial, v) = \ell_v, \forall v \in \tau$$

## Key facts.

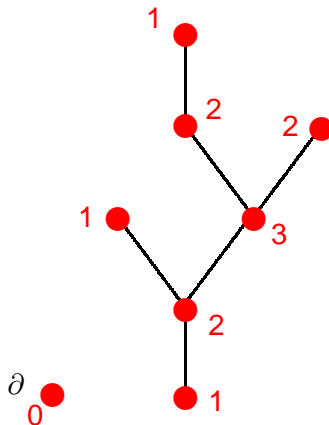
- Vertices of  $\tau$  become vertices of  $M$
- The **label** in the tree becomes the **distance** from the root in the map.

Coding of **more general maps**: Bouttier, Di Francesco, Guitter (2004)

# Schaeffer's bijection between quadrangulations and well-labeled trees



well-labeled tree

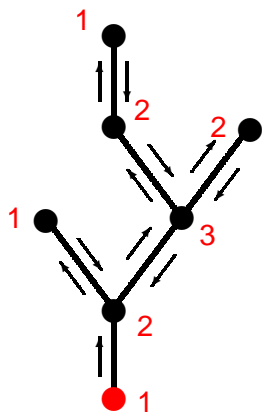


quadrangulation

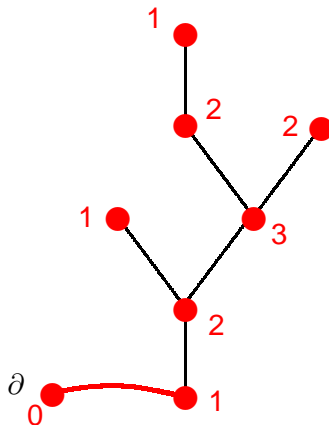
## Rules.

- add extra vertex  $\partial$  labeled 0
- follow the contour of the tree, connect each vertex to the **last visited** vertex with **smaller label**

# Schaeffer's bijection between quadrangulations and well-labeled trees



well-labeled tree

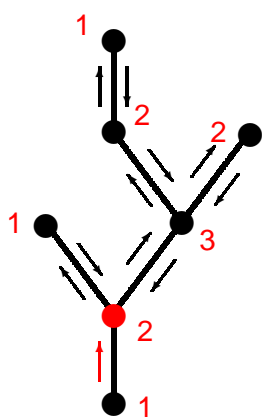


quadrangulation

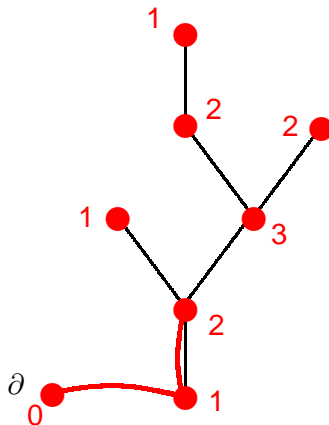
## Rules.

- add extra vertex  $\partial$  labeled 0
- follow the contour of the tree, connect each vertex to the **last visited** vertex with **smaller label**

# Schaeffer's bijection between quadrangulations and well-labeled trees



well-labeled tree



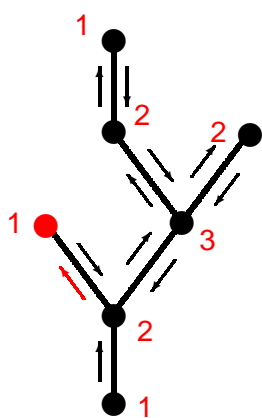
quadrangulation

## Rules.

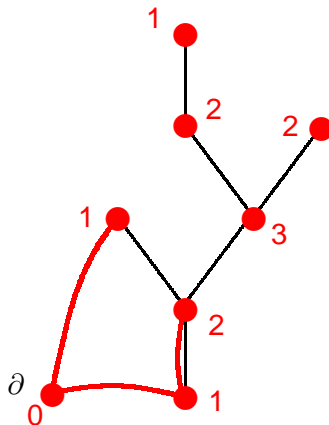
- add extra vertex  $\partial$  labeled 0
- follow the contour of the tree, connect each vertex to the **last visited** vertex with **smaller label**



# Schaeffer's bijection between quadrangulations and well-labeled trees



well-labeled tree

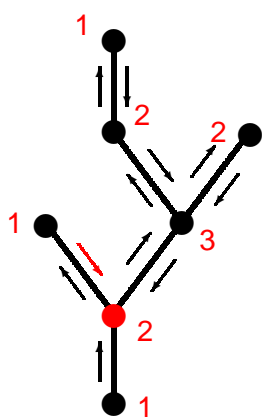


quadrangulation

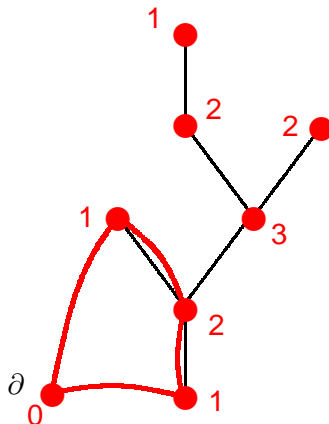
## Rules.

- add extra vertex  $\partial$  labeled 0
- follow the contour of the tree, connect each vertex to the **last visited** vertex with **smaller label**

# Schaeffer's bijection between quadrangulations and well-labeled trees



well-labeled tree

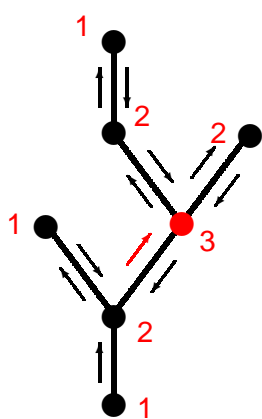


quadrangulation

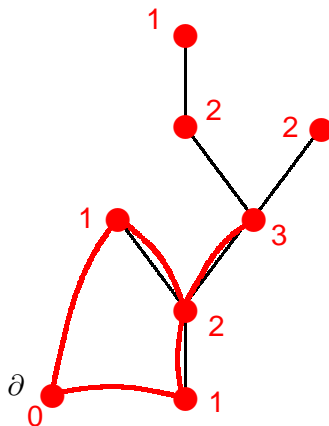
## Rules.

- add extra vertex  $\partial$  labeled 0
- follow the contour of the tree, connect each vertex to the **last visited** vertex with **smaller label**

## Schaeffer's bijection between quadrangulations and well-labeled trees



well-labeled tree

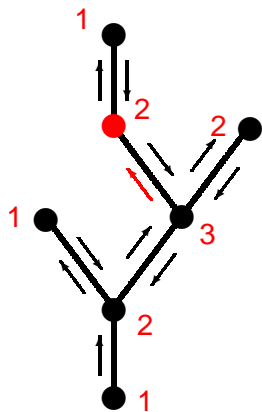


quadrangulation

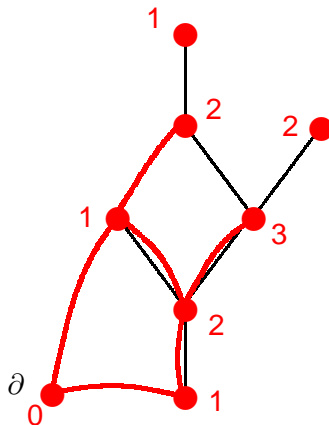
## Rules.

- add extra vertex  $\partial$  labeled 0
- follow the contour of the tree, connect each vertex to the **last visited** vertex with **smaller label**

# Schaeffer's bijection between quadrangulations and well-labeled trees



well-labeled tree

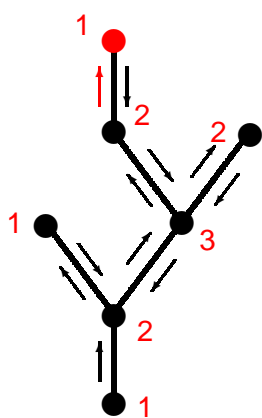


quadrangulation

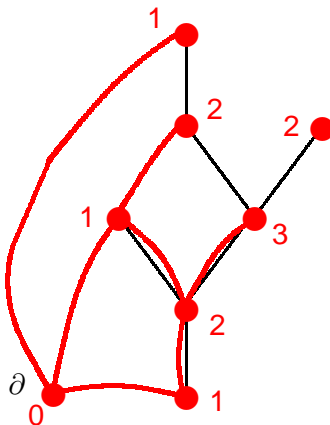
## Rules.

- add extra vertex  $\partial$  labeled 0
- follow the contour of the tree, connect each vertex to the **last visited** vertex with **smaller label**

# Schaeffer's bijection between quadrangulations and well-labeled trees



well-labeled tree

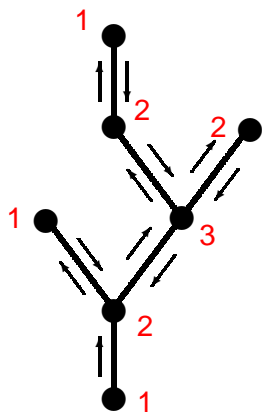


quadrangulation

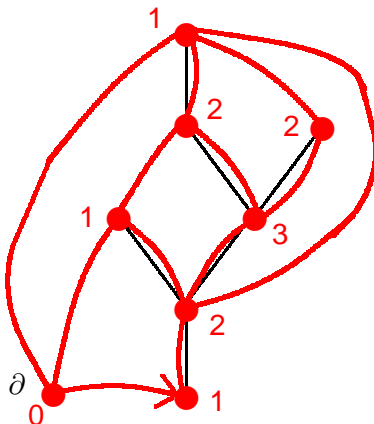
## Rules.

- add extra vertex  $\partial$  labeled 0
- follow the contour of the tree, connect each vertex to the **last visited** vertex with **smaller label**

# Schaeffer's bijection between quadrangulations and well-labeled trees



well-labeled tree



quadrangulation

## Rules.

- add extra vertex  $\partial$  labeled 0
- follow the contour of the tree, connect each vertex to the **last visited** vertex with **smaller label**

# General strategy

Understand continuous limits of **trees** (“easy”)

in order to understand continuous limits of **maps** (“more difficult”)

**Key point.** The bijections with trees allow us to handle distances from the root vertex, but **not** distances between two arbitrary vertices of the map (required if one wants to get Gromov-Hausdorff convergence)

# General strategy

Understand continuous limits of **trees** (“easy”)

in order to understand continuous limits of **maps** (“more difficult”)

**Key point.** The bijections with trees allow us to handle distances from the root vertex, but **not** distances between two arbitrary vertices of the map (required if one wants to get Gromov-Hausdorff convergence)



### 3. Asymptotics for trees

#### The case of planar trees

$$T_n^{\text{planar}} = \{\text{planar trees with } n \text{ edges}\}$$

#### Theorem (reformulation of Aldous 1993)

For every  $n$ , let  $\tau_n$  be a random tree uniformly distributed over  $T_n^{\text{planar}}$ . Then,

$$(\tau_n, \frac{1}{\sqrt{2n}} d_{\text{gr}}) \longrightarrow (\mathcal{T}_{\mathbf{e}}, d_{\mathbf{e}}) \quad \text{as } n \rightarrow \infty$$

in distribution, in the Gromov-Hausdorff sense.

Here  $(\mathcal{T}_{\mathbf{e}}, d_{\mathbf{e}})$  is the CRT (Continuum Random Tree)

The notation  $(\mathcal{T}_{\mathbf{e}}, d_{\mathbf{e}})$  comes from the fact that the CRT is the tree **coded by a Brownian excursion  $\mathbf{e}$**

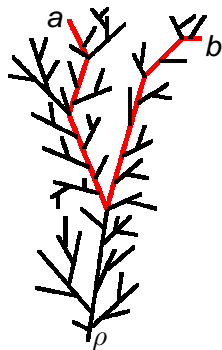
# Definition of the CRT: notion of a real tree

## Definition

A real tree is a (compact) metric space  $\mathcal{T}$  such that:

- any two points  $a, b \in \mathcal{T}$  are joined by a unique arc
- this arc is isometric to a line segment

It is a rooted real tree if there is a distinguished point  $\rho$ , called the root.



**Remark.** A real tree can have

- infinitely many branching points
- (uncountably) infinitely many leaves

**Fact.** The coding of discrete trees by contour functions (Dyck paths) can be extended to real trees.

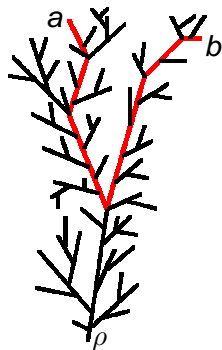
# Definition of the CRT: notion of a real tree

## Definition

A real tree is a (compact) metric space  $\mathcal{T}$  such that:

- any two points  $a, b \in \mathcal{T}$  are joined by a unique arc
- this arc is isometric to a line segment

It is a rooted real tree if there is a distinguished point  $\rho$ , called the root.



**Remark.** A real tree can have

- infinitely many branching points
- (uncountably) infinitely many leaves

**Fact.** The coding of discrete trees by contour functions (Dyck paths) can be extended to real trees.

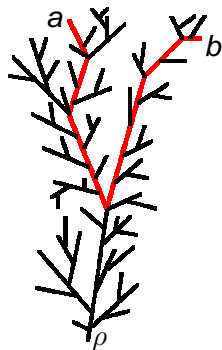
# Definition of the CRT: notion of a real tree

## Definition

A real tree is a (compact) metric space  $\mathcal{T}$  such that:

- any two points  $a, b \in \mathcal{T}$  are joined by a unique arc
- this arc is isometric to a line segment

It is a rooted real tree if there is a distinguished point  $\rho$ , called the root.



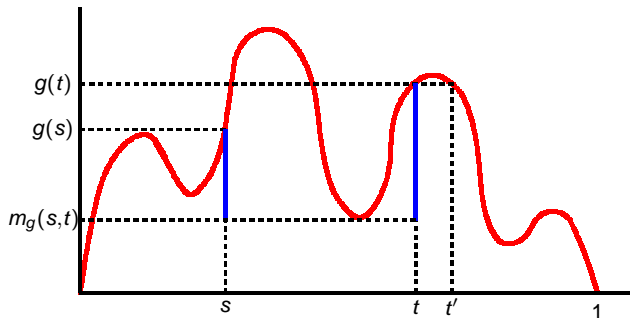
**Remark.** A real tree can have

- infinitely many branching points
- (uncountably) infinitely many leaves

**Fact.** The coding of discrete trees by contour functions (Dyck paths) can be extended to real trees.

# The real tree coded by a function $g$

$g : [0, 1] \longrightarrow [0, \infty)$   
continuous,  
 $g(0) = g(1) = 0$



$$m_g(s, t) = m_g(t, s) = \min_{s \leq r \leq t} g(r)$$

$$d_g(s, t) = g(s) + g(t) - 2m_g(s, t)$$

$$t \sim t' \text{ iff } d_g(t, t') = 0$$

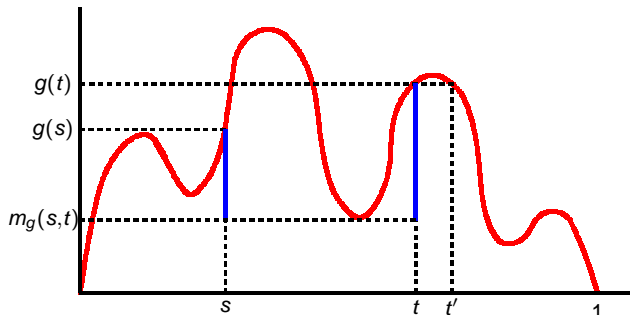
## Proposition (Duquesne-LG)

$\mathcal{T}_g := [0, 1] / \sim$  equipped with  $d_g$  is a real tree, called the tree coded by  $g$ . It is rooted at  $\rho = 0$ .

**Remark.**  $\mathcal{T}_g$  inherits a “lexicographical order” from the coding.

# The real tree coded by a function $g$

$g : [0, 1] \longrightarrow [0, \infty)$   
continuous,  
 $g(0) = g(1) = 0$



$$m_g(s, t) = m_g(t, s) = \min_{s \leq r \leq t} g(r)$$

$$d_g(s, t) = g(s) + g(t) - 2m_g(s, t)$$

$$t \sim t' \text{ iff } d_g(t, t') = 0$$

## Proposition (Duquesne-LG)

$\mathcal{T}_g := [0, 1] / \sim$  equipped with  $d_g$  is a real tree, called the tree coded by  $g$ . It is rooted at  $\rho = 0$ .

**Remark.**  $\mathcal{T}_g$  inherits a “lexicographical order” from the coding.

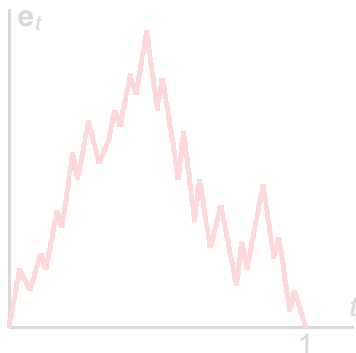
# Back to Aldous' theorem and the CRT

Aldous' theorem:  $\tau_n$  uniformly distributed over  $T_n^{\text{planar}}$

$$(\tau_n, \frac{1}{\sqrt{2n}} d_{\text{gr}}) \xrightarrow[n \rightarrow \infty]{(d)} (\mathcal{T}_e, d_e)$$

in the Gromov-Hausdorff sense.

The limit  $(\mathcal{T}_e, d_e)$  is the (random) real tree coded by a Brownian excursion  $e$ .



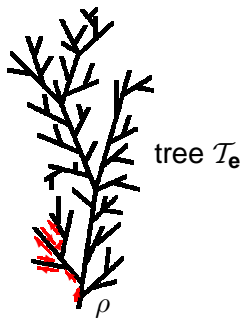
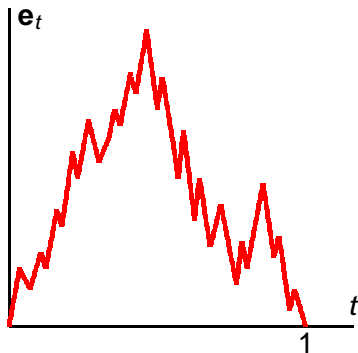
# Back to Aldous' theorem and the CRT

Aldous' theorem:  $\tau_n$  uniformly distributed over  $T_n^{\text{planar}}$

$$(\tau_n, \frac{1}{\sqrt{2n}} d_{\text{gr}}) \xrightarrow[n \rightarrow \infty]{(d)} (\mathcal{T}_{\mathbf{e}}, d_{\mathbf{e}})$$

in the Gromov-Hausdorff sense.

The limit  $(\mathcal{T}_{\mathbf{e}}, d_{\mathbf{e}})$  is the (random) real tree coded by a Brownian excursion  $\mathbf{e}$ .





# Assigning labels to a real tree

Need to assign (random) labels to the vertices of a real tree  $(\mathcal{T}, d)$

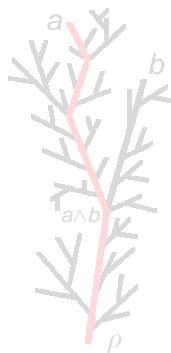
$(Z_a)_{a \in \mathcal{T}}$ : Brownian motion indexed by  $(\mathcal{T}, d)$   
= centered Gaussian process such that

- $Z_\rho = 0$  ( $\rho$  root of  $\mathcal{T}$ )
- $E[(Z_a - Z_b)^2] = d(a, b), \quad a, b \in \mathcal{T}$

Labels evolve like Brownian motion along the branches of the tree:

- The label  $Z_a$  is the value at time  $d(\rho, a)$  of a standard Brownian motion
- Similar property for  $Z_b$ , but one uses
  - ▶ the same BM between 0 and  $d(\rho, a \wedge b)$
  - ▶ an independent BM between  $d(\rho, a \wedge b)$  and  $d(\rho, b)$

**Problem.** The positivity constraint is not satisfied !

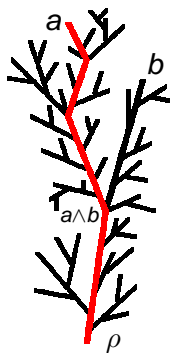


# Assigning labels to a real tree

Need to assign (random) labels to the vertices of a real tree  $(\mathcal{T}, d)$

$(Z_a)_{a \in \mathcal{T}}$ : Brownian motion indexed by  $(\mathcal{T}, d)$   
= centered Gaussian process such that

- $Z_\rho = 0$  ( $\rho$  root of  $\mathcal{T}$ )
- $E[(Z_a - Z_b)^2] = d(a, b), \quad a, b \in \mathcal{T}$



Labels evolve like Brownian motion along the branches of the tree:

- The label  $Z_a$  is the value at time  $d(\rho, a)$  of a standard Brownian motion
- Similar property for  $Z_b$ , but one uses
  - ▶ the same BM between 0 and  $d(\rho, a \wedge b)$
  - ▶ an independent BM between  $d(\rho, a \wedge b)$  and  $d(\rho, b)$

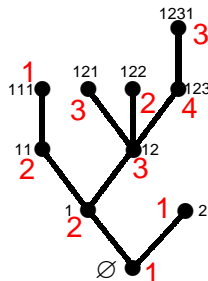
**Problem.** The positivity constraint is not satisfied !

# The scaling limit of well-labeled trees

Recall  $\mathbb{T}_n = \{\text{well-labeled trees with } n \text{ edges}\}$   
 $(\theta_n, (\ell_v^n)_{v \in \theta_n})$  uniformly distributed over  $\mathbb{T}_n$

## Rescaling:

- Distances on  $\theta_n$  are rescaled by  $\frac{1}{\sqrt{n}}$  (Aldous' theorem)
- Labels  $\ell_v^n$  are rescaled by  $\frac{1}{\sqrt{\sqrt{n}}} = \frac{1}{n^{1/4}}$  ("central limit theorem")



## Fact

The scaling limit of  $(\theta_n, (\ell_v^n)_{v \in \theta_n})$  is  $(\mathcal{T}_e, (\bar{Z}_a)_{a \in \mathcal{T}_e})$ , where

- $\mathcal{T}_e$  is the CRT
- $(Z_a)_{a \in \mathcal{T}_e}$  is Brownian motion indexed by the CRT
- $\bar{Z}_a = Z_a - Z_*$ , where  $Z_* = \min\{Z_a, a \in \mathcal{T}_e\}$
- $\mathcal{T}_e$  is re-rooted at vertex  $\rho_*$  minimizing  $Z$

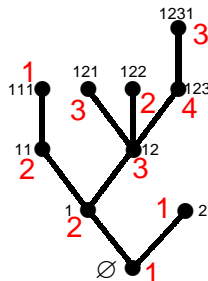
# The scaling limit of well-labeled trees

Recall  $\mathbb{T}_n = \{\text{well-labeled trees with } n \text{ edges}\}$

$(\theta_n, (\ell_v^n)_{v \in \theta_n})$  uniformly distributed over  $\mathbb{T}_n$

## Rescaling:

- Distances on  $\theta_n$  are rescaled by  $\frac{1}{\sqrt{n}}$  (Aldous' theorem)
- Labels  $\ell_v^n$  are rescaled by  $\frac{1}{\sqrt{\sqrt{n}}} = \frac{1}{n^{1/4}}$  ("central limit theorem")



## Fact

The scaling limit of  $(\theta_n, (\ell_v^n)_{v \in \theta_n})$  is  $(\mathcal{T}_e, (\bar{Z}_a)_{a \in \mathcal{T}_e})$ , where

- $\mathcal{T}_e$  is the CRT
- $(Z_a)_{a \in \mathcal{T}_e}$  is Brownian motion indexed by the CRT
- $\bar{Z}_a = Z_a - Z_*$ , where  $Z_* = \min\{Z_a, a \in \mathcal{T}_e\}$
- $\mathcal{T}_e$  is re-rooted at vertex  $\rho_*$  minimizing  $Z$

# Application to the radius of a planar map

## Recall

- Schaeffer's bijection : quadrangulations  $\leftrightarrow$  well-labeled trees
- labels on the tree correspond to distances from the root in the map

## Theorem (Chassaing-Schaeffer 2004)

*Let  $R_n$  be the maximal distance from the root in a quadrangulation with  $n$  faces chosen at random. Then,*

$$n^{-1/4} R_n \xrightarrow[n \rightarrow \infty]{(d)} \left(\frac{8}{9}\right)^{1/4} (\max Z - \min Z)$$

*where  $(Z_a)_{a \in \mathcal{T}_e}$  is Brownian motion indexed by the CRT.*

Extensions to much more general planar maps (including triangulations, etc.) by

- Marckert-Miermont (2006), Miermont, Miermont-Weill (2007), ...

$\Rightarrow$  Strongly suggests the **universality** of the scaling limit of maps.

# Application to the radius of a planar map

## Recall

- Schaeffer's bijection : quadrangulations  $\leftrightarrow$  well-labeled trees
- labels on the tree correspond to distances from the root in the map

## Theorem (Chassaing-Schaeffer 2004)

*Let  $R_n$  be the maximal distance from the root in a quadrangulation with  $n$  faces chosen at random. Then,*

$$n^{-1/4} R_n \xrightarrow[n \rightarrow \infty]{(d)} \left(\frac{8}{9}\right)^{1/4} (\max Z - \min Z)$$

*where  $(Z_a)_{a \in \mathcal{T}_e}$  is Brownian motion indexed by the CRT.*

Extensions to much more general planar maps (including triangulations, etc.) by

- Marckert-Miermont (2006), Miermont, Miermont-Weill (2007), ...

$\Rightarrow$  Strongly suggests the **universality** of the scaling limit of maps.

## 4. The scaling limit of planar maps

$\mathbb{M}_n^{2p} = \{\text{rooted } 2p\text{-angulations with } n \text{ faces}\}$  (**bipartite case**)

$M_n$  uniform over  $\mathbb{M}_n^{2p}$ ,  $V(M_n)$  vertex set of  $M_n$ ,  $d_{\text{gr}}$  graph distance

### Theorem (The scaling limit of $2p$ -angulations)

At least along a sequence  $n_k \uparrow \infty$ , we have

$$(V(M_{n_k}), c_p \frac{1}{n_k^{1/4}} d_{\text{gr}}) \xrightarrow[n_k \rightarrow \infty]{(d)} (\mathbf{m}_\infty, D)$$

in the sense of the Gromov-Hausdorff distance.

Furthermore,  $\mathbf{m}_\infty = \mathcal{T}_e / \approx$  where

- $\mathcal{T}_e$  is the **CRT** (re-rooted at vertex  $\rho_*$  minimizing  $Z$ )
- $(Z_a)_{a \in \mathcal{T}_e}$  is **Brownian motion indexed by**  $\mathcal{T}_e$ , and  $\bar{Z}_a = Z_a - \min Z$
- $\approx$  equivalence relation on  $\mathcal{T}_e$ :  $a \approx b \Leftrightarrow \bar{Z}_a = \bar{Z}_b = \min_{c \in [a,b]} \bar{Z}_c$   
( $[a, b]$  lexicographical interval between  $a$  and  $b$  in the tree)
- $D$  distance on  $\mathbf{m}_\infty$  such that  $D(\rho_*, a) = \bar{Z}_a$   
 $D$  induces the **quotient topology** on  $\mathbf{m}_\infty = \mathcal{T}_e / \approx$





# Consequence and open problems

## Corollary

*The topological type of any Gromov-Hausdorff sequential limit of  $(V(M_n), n^{-1/4}d_{\text{gr}})$  is determined:*

$$\mathbf{m}_\infty = \mathcal{T}_{\mathbf{e}} / \approx \quad \text{with the quotient topology.}$$

## Open problems

- Identify the distance  $D$  on  $\mathbf{m}_\infty$   
(would imply that there is no need for taking a subsequence)
- Show that  $D$  does not depend on  $p$   
(universality property, expect same limit for triangulations, etc.)

STILL MUCH CAN BE PROVED ABOUT THE LIMIT !

The limiting space  $(\mathbf{m}_\infty, D)$  is called the **Brownian map** [Marckert, Mokkadem 2006, with a different approach]

# Consequence and open problems

## Corollary

*The topological type of any Gromov-Hausdorff sequential limit of  $(V(M_n), n^{-1/4}d_{\text{gr}})$  is determined:*

$$\mathbf{m}_\infty = \mathcal{T}_{\mathbf{e}} / \approx \quad \text{with the quotient topology.}$$

## Open problems

- **Identify the distance  $D$  on  $\mathbf{m}_\infty$**   
(would imply that there is no need for taking a subsequence)
- Show that  $D$  does not depend on  $p$   
(universality property, expect same limit for triangulations, etc.)

STILL MUCH CAN BE PROVED ABOUT THE LIMIT !

The limiting space  $(\mathbf{m}_\infty, D)$  is called the **Brownian map** [Marckert, Mokkadem 2006, with a different approach]

# Consequence and open problems

## Corollary

*The topological type of any Gromov-Hausdorff sequential limit of  $(V(M_n), n^{-1/4}d_{\text{gr}})$  is determined:*

$$\mathbf{m}_\infty = \mathcal{T}_{\mathbf{e}} / \approx \quad \text{with the quotient topology.}$$

## Open problems

- **Identify the distance  $D$  on  $\mathbf{m}_\infty$**   
(would imply that there is no need for taking a subsequence)
- Show that  $D$  does not depend on  $p$   
(universality property, expect same limit for triangulations, etc.)

**STILL MUCH CAN BE PROVED ABOUT THE LIMIT !**

The limiting space  $(\mathbf{m}_\infty, D)$  is called the **Brownian map** [Marckert, Mokkadem 2006, with a different approach]

# Two theorems about the Brownian map

## Theorem (Hausdorff dimension)

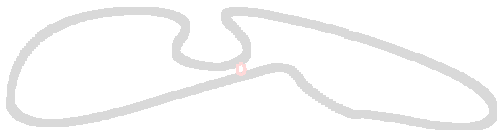
$$\dim(\mathbf{m}_\infty, D) = 4 \quad \text{a.s.}$$

(Already “known” in the physics literature.)

## Theorem (topological type, LG-Paulin 2007)

*Almost surely,  $(\mathbf{m}_\infty, D)$  is homeomorphic to the 2-sphere  $\mathbb{S}^2$ .*

**Consequence:** for  $n$  large,  
no separating cycle of size  
 $o(n^{1/4})$  in  $M_n$ ,  
such that both sides have  
diameter  $\geq \varepsilon n^{1/4}$



Alternative proof of the homeomorphism theorem: Miermont (2008)

# Two theorems about the Brownian map

## Theorem (Hausdorff dimension)

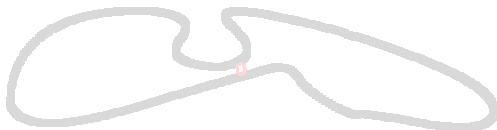
$$\dim(\mathbf{m}_\infty, D) = 4 \quad a.s.$$

(Already “known” in the physics literature.)

## Theorem (topological type, LG-Paulin 2007)

*Almost surely,  $(\mathbf{m}_\infty, D)$  is homeomorphic to the 2-sphere  $\mathbb{S}^2$ .*

**Consequence:** for  $n$  large,  
no separating cycle of size  
 $o(n^{1/4})$  in  $M_n$ ,  
such that both sides have  
diameter  $\geq \varepsilon n^{1/4}$



Alternative proof of the homeomorphism theorem: Miermont (2008)

# Two theorems about the Brownian map

## Theorem (Hausdorff dimension)

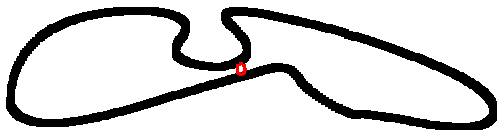
$$\dim(\mathbf{m}_\infty, D) = 4 \quad a.s.$$

(Already “known” in the physics literature.)

## Theorem (topological type, LG-Paulin 2007)

*Almost surely,  $(\mathbf{m}_\infty, D)$  is homeomorphic to the 2-sphere  $\mathbb{S}^2$ .*

**Consequence:** for  $n$  large,  
no separating cycle of size  
 $o(n^{1/4})$  in  $M_n$ ,  
such that both sides have  
diameter  $\geq \varepsilon n^{1/4}$



Alternative proof of the homeomorphism theorem: Miermont (2008)

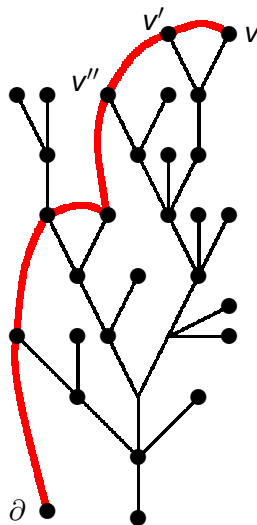
## 5. Geodesics in the Brownian map

### Geodesics in quadrangulations

Use Schaeffer's bijection between quadrangulations and well-labeled trees.

To construct a geodesic from  $v$  to  $\partial$ :

- Look for the last visited vertex (before  $v$ ) with label  $\ell_v - 1$ . Call it  $v'$ .
- Proceed in the same way from  $v'$  to get a vertex  $v''$ .
- And so on.
- Eventually one reaches the root  $\partial$ .



# Simple geodesics in the Brownian map

Brownian map:  $\mathbf{m}_\infty = \mathcal{T}_\mathbf{e} / \approx$ , root  $\rho_*$

$\prec$  lexicographical order on  $\mathcal{T}_\mathbf{e}$

Recall  $D(\rho_*, a) = \bar{Z}_a$  (labels on  $\mathcal{T}_\mathbf{e}$ )

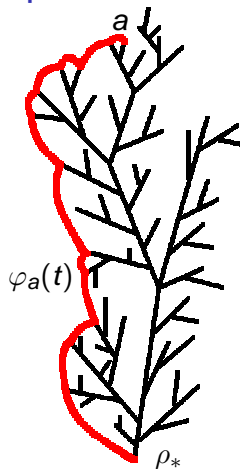
Fix  $a \in \mathcal{T}_\mathbf{e}$  and for  $t \in [0, \bar{Z}_a]$ , set

$$\varphi_a(t) = \sup\{b \prec a : \bar{Z}_b = t\}$$

(same formula as in the discrete case !)

Then  $(\varphi_a(t))_{0 \leq t \leq \bar{Z}_a}$  is a geodesic from  $\rho_*$  to  $a$

(called a **simple geodesic**)



## Fact

*Simple geodesics visit only leaves of  $\mathcal{T}_\mathbf{e}$  (except possibly at the endpoint)*



# Simple geodesics in the Brownian map

Brownian map:  $\mathbf{m}_\infty = \mathcal{T}_e / \approx$ , root  $\rho_*$

$\prec$  lexicographical order on  $\mathcal{T}_e$

Recall  $D(\rho_*, a) = \bar{Z}_a$  (labels on  $\mathcal{T}_e$ )

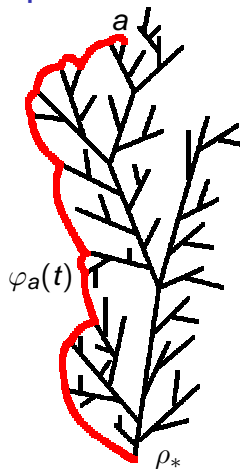
Fix  $a \in \mathcal{T}_e$  and for  $t \in [0, \bar{Z}_a]$ , set

$$\varphi_a(t) = \sup\{b \prec a : \bar{Z}_b = t\}$$

(same formula as in the discrete case !)

Then  $(\varphi_a(t))_{0 \leq t \leq \bar{Z}_a}$  is a geodesic from  $\rho_*$  to  $a$

(called a **simple geodesic**)



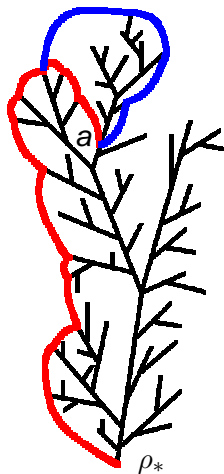
## Fact

*Simple geodesics visit only leaves of  $\mathcal{T}_e$  (except possibly at the endpoint)*

# How many simple geodesics from a given point ?

- If  $a$  is a leaf of  $\mathcal{T}_e$ , there is a unique simple geodesic from  $\rho_*$  to  $a$
- Otherwise, there are
  - ▶ 2 distinct simple geodesics if  $a$  is a simple point
  - ▶ 3 distinct simple geodesics if  $a$  is a branching point

(3 is the maximal multiplicity in  $\mathcal{T}_e$ )



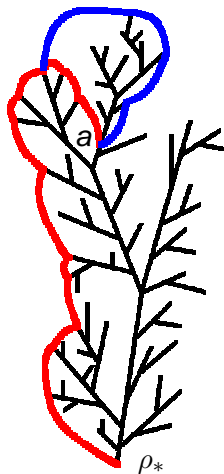
## Proposition (key result)

*All geodesics from the root are simple geodesics.*

# How many simple geodesics from a given point ?

- If  $a$  is a leaf of  $\mathcal{T}_e$ , there is a unique simple geodesic from  $\rho_*$  to  $a$
- Otherwise, there are
  - ▶ 2 distinct simple geodesics if  $a$  is a simple point
  - ▶ 3 distinct simple geodesics if  $a$  is a branching point

(3 is the maximal multiplicity in  $\mathcal{T}_e$ )



## Proposition (key result)

*All geodesics from the root are simple geodesics.*

# The main result about geodesics

Define the skeleton of  $\mathcal{T}_{\mathbf{e}}$  by  $\text{Sk}(\mathcal{T}_{\mathbf{e}}) = \mathcal{T}_{\mathbf{e}} \setminus \{\text{leaves of } \mathcal{T}_{\mathbf{e}}\}$  and set

$$\text{Skel} = \pi(\text{Sk}(\mathcal{T}_{\mathbf{e}})) \quad (\pi : \mathcal{T}_{\mathbf{e}} \rightarrow \mathcal{T}_{\mathbf{e}}/\approx = \mathbf{m}_{\infty} \text{ canonical projection})$$

Then

- the restriction of  $\pi$  to  $\text{Sk}(\mathcal{T}_{\mathbf{e}})$  is a homeomorphism onto  $\text{Skel}$
- $\dim(\text{Skel}) = 2$  (recall  $\dim(\mathbf{m}_{\infty}) = 4$ )

## Theorem (Geodesics from the root)

Let  $x \in \mathbf{m}_{\infty}$ . Then,

- if  $x \notin \text{Skel}$ , there is a unique geodesic from  $\rho_*$  to  $x$
- if  $x \in \text{Skel}$ , the number of distinct geodesics from  $\rho_*$  to  $x$  is the multiplicity  $m(x)$  of  $x$  in  $\text{Skel}$  (note:  $m(x) \leq 3$ ).

## Remarks

- $\text{Skel}$  is the cut-locus of  $\mathbf{m}_{\infty}$  relative to  $\rho$ : cf classical Riemannian geometry [Poincaré, Myers, ...], where the cut-locus is a tree.
- same results if  $\rho_*$  replaced by a point chosen “at random” in  $\mathbf{m}_{\infty}$ .
- other approach to the uniqueness of geodesics: Miermont (2007)

# The main result about geodesics

Define the skeleton of  $\mathcal{T}_{\mathbf{e}}$  by  $\text{Sk}(\mathcal{T}_{\mathbf{e}}) = \mathcal{T}_{\mathbf{e}} \setminus \{\text{leaves of } \mathcal{T}_{\mathbf{e}}\}$  and set

$$\text{Skel} = \pi(\text{Sk}(\mathcal{T}_{\mathbf{e}})) \quad (\pi : \mathcal{T}_{\mathbf{e}} \rightarrow \mathcal{T}_{\mathbf{e}} / \approx = \mathbf{m}_{\infty} \text{ canonical projection})$$

Then

- the restriction of  $\pi$  to  $\text{Sk}(\mathcal{T}_{\mathbf{e}})$  is a homeomorphism onto  $\text{Skel}$
- $\dim(\text{Skel}) = 2$  (recall  $\dim(\mathbf{m}_{\infty}) = 4$ )

## Theorem (Geodesics from the root)

Let  $x \in \mathbf{m}_{\infty}$ . Then,

- if  $x \notin \text{Skel}$ , there is a unique geodesic from  $\rho_*$  to  $x$
- if  $x \in \text{Skel}$ , the number of distinct geodesics from  $\rho_*$  to  $x$  is the multiplicity  $m(x)$  of  $x$  in  $\text{Skel}$  (note:  $m(x) \leq 3$ ).

## Remarks

- $\text{Skel}$  is the cut-locus of  $\mathbf{m}_{\infty}$  relative to  $\rho$ : cf classical Riemannian geometry [Poincaré, Myers, ...], where the cut-locus is a tree.
- same results if  $\rho_*$  replaced by a point chosen “at random” in  $\mathbf{m}_{\infty}$ .
- other approach to the uniqueness of geodesics: Miermont (2007)

# The main result about geodesics

Define the skeleton of  $\mathcal{T}_{\mathbf{e}}$  by  $\text{Sk}(\mathcal{T}_{\mathbf{e}}) = \mathcal{T}_{\mathbf{e}} \setminus \{\text{leaves of } \mathcal{T}_{\mathbf{e}}\}$  and set

$$\text{Skel} = \pi(\text{Sk}(\mathcal{T}_{\mathbf{e}})) \quad (\pi : \mathcal{T}_{\mathbf{e}} \rightarrow \mathcal{T}_{\mathbf{e}} / \approx = \mathbf{m}_{\infty} \text{ canonical projection})$$

Then

- the restriction of  $\pi$  to  $\text{Sk}(\mathcal{T}_{\mathbf{e}})$  is a homeomorphism onto  $\text{Skel}$
- $\dim(\text{Skel}) = 2$  (recall  $\dim(\mathbf{m}_{\infty}) = 4$ )

## Theorem (Geodesics from the root)

Let  $x \in \mathbf{m}_{\infty}$ . Then,

- if  $x \notin \text{Skel}$ , there is a unique geodesic from  $\rho_*$  to  $x$
- if  $x \in \text{Skel}$ , the number of distinct geodesics from  $\rho_*$  to  $x$  is the multiplicity  $m(x)$  of  $x$  in  $\text{Skel}$  (note:  $m(x) \leq 3$ ).

## Remarks

- $\text{Skel}$  is the cut-locus of  $\mathbf{m}_{\infty}$  relative to  $\rho$ : cf classical Riemannian geometry [Poincaré, Myers, ...], where the cut-locus is a tree.
- same results if  $\rho_*$  replaced by a point chosen “at random” in  $\mathbf{m}_{\infty}$ .
- other approach to the uniqueness of geodesics: Miermont (2007)

# Confluence property of geodesics

**Fact:** Two simple geodesics coincide near the root.  
(easy from the definition)

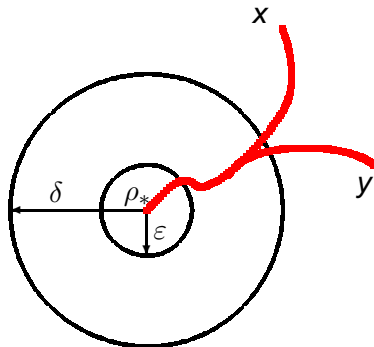
## Corollary

Given  $\delta > 0$ , there exists  $\varepsilon > 0$  s.t.

- if  $D(\rho_*, x) \geq \delta$ ,  $D(\rho_*, y) \geq \delta$
- if  $\gamma$  is any geodesic from  $\rho_*$  to  $x$
- if  $\gamma'$  is any geodesic from  $\rho_*$  to  $y$

then

$$\gamma(t) = \gamma'(t) \quad \text{for all } t \leq \varepsilon$$



“Only one way” of leaving  $\rho_*$  along a geodesic.  
(also true if  $\rho_*$  is replaced by a typical point of  $\mathbf{m}_\infty$ )

# Uniqueness of geodesics in discrete maps

$M_n$  uniform distributed over  $\mathbb{M}_n^{2p} = \{2p - \text{angulations with } n \text{ faces}\}$

$V(M_n)$  set of vertices of  $M_n$ ,  $\partial$  root vertex of  $M_n$ ,  $d_{\text{gr}}$  graph distance

For  $v \in V(M_n)$ ,  $\text{Geo}(\partial \rightarrow v) = \{\text{geodesics from } \partial \text{ to } v\}$

If  $\gamma, \gamma'$  are two discrete paths (with the same length)

$$d(\gamma, \gamma') = \max_i d_{\text{gr}}(\gamma(i), \gamma'(i))$$

## Corollary

Let  $\delta > 0$ . Then,

$$\frac{1}{n} \# \{v \in V(M_n) : \exists \gamma, \gamma' \in \text{Geo}(\partial \rightarrow v), d(\gamma, \gamma') \geq \delta n^{1/4}\} \xrightarrow{n \rightarrow \infty} 0$$

Macroscopic uniqueness of geodesics, also true for  
“approximate geodesics” = paths with length  $d_{\text{gr}}(\partial, v) + o(n^{1/4})$



# Uniqueness of geodesics in discrete maps

$M_n$  uniform distributed over  $\mathbb{M}_n^{2p} = \{2p - \text{angulations with } n \text{ faces}\}$

$V(M_n)$  set of vertices of  $M_n$ ,  $\partial$  root vertex of  $M_n$ ,  $d_{\text{gr}}$  graph distance

For  $v \in V(M_n)$ ,  $\text{Geo}(\partial \rightarrow v) = \{\text{geodesics from } \partial \text{ to } v\}$

If  $\gamma, \gamma'$  are two discrete paths (with the same length)

$$d(\gamma, \gamma') = \max_i d_{\text{gr}}(\gamma(i), \gamma'(i))$$

## Corollary

Let  $\delta > 0$ . Then,

$$\frac{1}{n} \#\{v \in V(M_n) : \exists \gamma, \gamma' \in \text{Geo}(\partial \rightarrow v), d(\gamma, \gamma') \geq \delta n^{1/4}\} \xrightarrow{n \rightarrow \infty} 0$$

**Macroscopic** uniqueness of geodesics, also true for  
“approximate geodesics” = paths with length  $d_{\text{gr}}(\partial, v) + o(n^{1/4})$

# Exceptional points in discrete maps

$M_n$  uniformly distributed  $2p$ -angulation with  $n$  faces

For  $v \in V(M_n)$ , and  $\delta > 0$ , set

$$\text{Mult}_\delta(v) = \max\{k : \exists \gamma_1, \dots, \gamma_k \in \text{Geo}(\partial, v), d(\gamma_i, \gamma_j) \geq \delta n^{1/4} \text{ if } i \neq j\}$$

(number of “macroscopically different” geodesics from  $\partial$  to  $v$ )

## Corollary

1. For every  $\delta > 0$ ,

$$P[\exists v \in V(M_n) : \text{Mult}_\delta(v) \geq 4] \xrightarrow[n \rightarrow \infty]{} 0$$

2. But

$$\lim_{\delta \rightarrow 0} \left( \liminf_{n \rightarrow \infty} P[\exists v \in V(M_n) : \text{Mult}_\delta(v) = 3] \right) = 1$$

There can be at most **3 macroscopically different geodesics** from  $\partial$  to an arbitrary vertex of  $M_n$ .

**Remark.**  $\partial$  can be replaced by a vertex chosen at random in  $M_n$ .

# Exceptional points in discrete maps

$M_n$  uniformly distributed  $2p$ -angulation with  $n$  faces

For  $v \in V(M_n)$ , and  $\delta > 0$ , set

$$\text{Mult}_\delta(v) = \max\{k : \exists \gamma_1, \dots, \gamma_k \in \text{Geo}(\partial, v), d(\gamma_i, \gamma_j) \geq \delta n^{1/4} \text{ if } i \neq j\}$$

(number of “macroscopically different” geodesics from  $\partial$  to  $v$ )

## Corollary

1. For every  $\delta > 0$ ,

$$P[\exists v \in V(M_n) : \text{Mult}_\delta(v) \geq 4] \xrightarrow[n \rightarrow \infty]{} 0$$

2. But

$$\lim_{\delta \rightarrow 0} \left( \liminf_{n \rightarrow \infty} P[\exists v \in V(M_n) : \text{Mult}_\delta(v) = 3] \right) = 1$$

There can be at most **3 macroscopically different geodesics** from  $\partial$  to an arbitrary vertex of  $M_n$ .

**Remark.**  $\partial$  can be replaced by a vertex chosen at random in  $M_n$ .

## A few references

BENJAMINI: Random planar metrics. Preprint.

BOUQUIER, DI FRANCESCO, GUITTER: Planar maps as labeled mobiles. *Electr. J. Combinatorics* **11**, #R69 (2004)

BOUQUIER, GUITTER: The 3-point function... *J. Stat. Mech.* (2008)

BOUQUIER, GUITTER: Statistics of geodesics ... *J. Physics A* (2008)

LE GALL: The topological structure of scaling limits of large planar maps. *Invent. Math.* **169**, 621-670 (2007)

LE GALL: Geodesics in large planar maps ... *Acta Math.*, to appear.

LE GALL, PAULIN: Scaling limits of bipartite planar maps are homeomorphic to the 2-sphere. *GAFA* **18**, 893-918 (2008)

MARCKERT, MIERMONT: Invariance principles for random bipartite planar maps. *Ann. Probab.* **35**, 1642-1705 (2007)

MARCKERT, MOKKADEM: Limit of normalized quadrangulations: The Brownian map. *Ann. Probab.* **34**, 2144-2102 (2006)

MIERMONT: Tessellations of random maps ... *Ann. ENS* (2009)

MIERMONT: On the sphericity of scaling limits ... *ECP* (2008)