# A Fokker-Planck model for two interacting populations of neurons

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### Outline

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- Fokker-Planck equation
- The stationnary problem
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- Generalized relative entropy
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# The neuroscience model



Synaptic strength between population i and j:

$$w_{ij} = \begin{cases} w_+ - w_I & i = j \\ w_- - w_I & i \neq j \end{cases}$$

 $w_+$  weight excitation between neurons of a same population  $w_-$  weight excitation between neurons of different populations  $w_I$  inhibitory weight coupling with all other neurons  $\lambda_i$  sensory input to the population i

The firing rates  $\nu_1 = \nu_1(t)$ ,  $\nu_2 = \nu_2(t)$  of two interacting neuron families may be modeled as follows (Wilson-Cowan):

$$\begin{cases} \dot{\nu_1} = -\nu_1 + \phi \left( \lambda_1 + \sum_{j=1,2} w_{1j} \nu_j \right) + \xi \\ \dot{\nu_2} = -\nu_2 + \phi \left( \lambda_2 + \sum_{j=1,2} w_{2j} \nu_j \right) + \xi \end{cases}$$

where  $\xi = \xi(t)$  is a white noise of standard deviation  $\beta^2$  (fluctuations) the function  $\phi(x)$  (transfer response) is a sigmoidal function given by:

$$\phi(x) = \frac{\nu_c}{1 + \exp(-\alpha(x/\nu_c - 1))},$$

with  $\alpha, \nu_c \in \mathbb{R}$ .

$$\lambda_2 = \lambda_1 + \Delta \lambda$$
,  $\Delta \lambda = 0$  or 0.1

**Remark**:  $\phi$  is strictly monotone and bounded.

[DM] G.Deco, D.Marti, Biological Cybernetics (2007)

Let f(t, x, y) be a distribution function for  $t \ge 0$  and  $\nu = (\nu_1, \nu_2) \in \Omega$ , s.t.:

$$\partial_t f + \nabla \cdot (Ff) - \frac{\beta^2}{2} \Delta f = 0, \quad \left(Ff - \frac{\beta^2}{2} \nabla f\right) \cdot n = 0 \quad (FP)$$

with the flux  $Ff = (-\nu + \Phi(\Lambda + W \cdot \nu)) f$  not deriving by a potential V:  $z_1 = \lambda + w_{11}\nu_1 + w_{12}\nu_2 \neq \lambda + w_{12}\nu_1 + w_{11}\nu_2 = z_2 \implies w_{12}\phi'(z_1) \neq w_{12}\phi'(z_2)$ 

Moreover F verifies:

 $\nabla \cdot F \leq 0 \tag{H1}$  $F \cdot n \leq 0 \tag{H2}$  $\int_{\Omega} f \, d\nu = 1 \tag{H3}$ 

[AC] A. Arnold, E.Carlen, EQUADIFF 99, Proc. Intern. Conf. Diff. Eqs. (2000)

#### Stationnary problem

Consider now the stationarry problem associated to (P):

$$\mathcal{A}f = -\frac{\beta^2}{2}\Delta f + \nabla \cdot (Ff) = 0 , \quad \left(Ff - \frac{\beta^2}{2}\nabla f\right) \cdot n = 0 \quad (S)$$

### **Theorem: Assume** (*H*2) and (*H*3), then there exists a unique positive solution $f_{\infty}(\nu)$ to (*S*).

**Proof:** Based on Krein-Rutman theorem : •  $T: L^2(\Omega) \to L^2(\Omega)$ , s.t.  $\forall g \in L^2(\Omega)$ , Tg = f, with f the unique solution of :

$$\mathcal{A}f + \rho f = g$$
 in  $\Omega$ ,  $(Ff - \frac{\beta^2}{2}\nabla f) \cdot n = 0$  on  $\partial \Omega$ 

•  $T: H^2 \to H^2$  is a compact operator, and  $T: K \to K$  strong. pos., with  $K = W^{2,2}_+(\Omega)$ . • KR th.  $\implies r(T) > 0$  and  $\exists g > 0$  s.t. Tg = r(T)g. So that,

$$\mathcal{A}f + \rho f = \lambda f, \quad f = r(T)g > 0, \quad \lambda = \frac{1}{r(T)} \quad \text{and}$$
$$\mathcal{A}f = (\lambda - \rho)f \quad \Rightarrow \ (\lambda - \rho)\int_{\Omega} f \, dx = 0 \quad \Rightarrow \ \rho = \lambda \quad \Rightarrow \ \mathcal{A}f = 0.$$

#### Time depending problem

We consider the parabolic problem:

$$\partial_t f + \mathcal{A}f = 0$$
,  $\left(Ff - \frac{\beta^2}{2}\nabla f\right) \cdot n = 0$  (P)

and the initial condition:  $f_0(\cdot) \in L^2(\Omega)$ 

# Theorem: Assume that (H1) holds,

then (P) has a unique solution f(t, x, y).

Consider the bilinear form associated to  $\mathcal{A}$ :

$$a(t,f,g) = \int_{\Omega} \frac{\beta^2}{2} \nabla f \cdot \nabla g \, d\nu - \int_{\Omega} fF \cdot \nabla g \, d\nu \,, \quad \forall f,g \in H^1(\Omega) \,, \qquad (a)$$

- a(t, f, g) is continuous,
- $a(t, f, g) + \rho < f, g >$  is coercive for  $\rho \in \mathbb{R}$  large enough.

**Remark** : Maximum principle doesn't apply.

Theorem: Let  $f_1$ ,  $f_2 > 0$  solutions of (P), and g > 0 a solution of :

$$\begin{cases} \partial_t g = -F \cdot \nabla g - \frac{\beta^2}{2} \Delta g, & \text{ in } \Omega \times [0, T], \\ \frac{\partial g}{\partial n} = 0 & \text{ on } \partial \Omega \end{cases}$$

then we have:

$$\frac{d}{dt} \int_{\Omega} gf_1 H \, d\nu = -\frac{\beta^2}{2} \int_{\Omega} gf_1 H'' \left| \nabla (f_2/f_1) \right|^2 \, d\nu \le 0 \,, \quad \forall \, H \text{ convex}.$$

**Proof**: 
$$\frac{\partial}{\partial t} \left[ gf_1 H \right] = -\nabla \cdot \left[ Fgf_1 H \right] + \frac{\beta^2}{2} \nabla \cdot \left[ g^2 \nabla \left( \frac{f_1}{g} H \right) \right] - \frac{\beta^2}{2} gf_1 H'' \left| \nabla \left( \tilde{f} \right) \right|^2$$

From this we can proove positivity of the solution f of (P) and its  $L^2$  convergence to the stationnary solution  $f_{\infty}$  of (S).

[MMP] P. Michel, S.Mischler, B.Perthame, J.Math. Pures Appl. (2005).

#### Numerical approximation - FVM

Let  $f^k(i,j) = f(k\Delta t, n_i, n_j)$  with  $n_i = (i + \frac{1}{2})\Delta N_1$ ,  $i = 0...N_1 - 1$  and  $n_j = (j + \frac{1}{2})\Delta N_2$ ,  $j = 0...N_2 - 1$ . Then, the discretised Fokker-Planck equation is given by:

$$f^{k+1}(i,j) = f^{k}(i,j) + \Delta t \left( F^{k}(i+1/2,j) - F^{k}(i-1/2,j) \right) / \Delta N_{1} + \Delta t \left( G^{k}(i,j+1/2) - G^{k}(i,j-1/2) \right) / \Delta N_{2},$$

with:  $F^k(i + \frac{1}{2}, j)$ ,  $G^k(i, j + \frac{1}{2})$  the fluxes at the interfaces:

$$F^{k}(i+1/2,j) = (-n_{i+1/2} + \Phi(\lambda + w_{11}n_{i+1/2} + w_{12}n_{j})) f^{k}(i+1/2,j) - \frac{\beta^{2}}{2\Delta N_{1}} (f^{k}(i+1,j) - f^{k}(i,j)), G^{k}(i,j+1/2) = (-n_{j+1/2} + \Phi(\lambda + w_{21}n_{i} + w_{22}n_{j+1/2})) f^{k}(i,j+1/2) - \frac{\beta^{2}}{2\Delta N_{2}} (f^{k}(i,j+1) - f^{k}(i,j)).$$

and we choose the most simple interpolation at the interfaces for f:

$$f^{k}(i+1/2,j) = \frac{f^{k}(i+1,j) + f^{k}(i,j)}{2}, \qquad f^{k}(i,j+1/2) = \frac{f^{k}(i,j+1) + f^{k}(i,j)}{2}$$

**Remark** adaptative  $\Delta t$  (gain factor 100)  $\Rightarrow$  for i, j s.t.  $f^k(i, j) \neq 0$  and  $\mathcal{F}^k(i, j) \neq 0$ :

$$\Delta t = \min_{i,j} \frac{f^k(i,j)}{2|\mathcal{F}^k(i,j)|}$$

## Computed quantities

Marginals of  $f(t, \nu_1, \nu_2)$  with respect to  $\nu_2$ , and to  $\nu_1$ :

$$\mathcal{N}_1(t,\nu_1) = \int_0^{\nu_M} f(t,\nu_1,\nu_2) d\nu_2 , \quad \mathcal{N}_2(t,\nu_2) = \int_0^{\nu_M} f(t,\nu_1,\nu_2) d\nu_1.$$

First order moments :

$$\mu_i(t) = \int \int_{\Omega} \nu_i f(\nu_1, \nu_2, t) d\nu_1 d\nu_2, \quad i = 1, 2$$

Second order moments :

$$\gamma_{ij}(t) = \int \int_{\Omega} \nu_i \nu_j f(\nu_1, \nu_2, t) d\nu_1 d\nu_2, \quad i, j = 1, 2.$$

Distributions  $\rho_i(t)$  with respect to the domains,  $\Omega_i$ , with i = 1, 2, 3:

$$\rho_i(t) = \int \int_{\Omega_i} f(\nu_1, \nu_2, t) d\nu_1 d\nu_2.$$

We choose  $N_1 = N_2 = 200$  points of discretisation, and compute the solution up to a precision of order  $10^{-10}$ , with the same values used in [1]. ( $\beta = 0.3$ ,  $\alpha = 4$ ,  $\nu_c = 20$ ,  $\lambda = 15$ .)

## Time evolution for the marginals



Evolution from one initial gaussian distribution centered in S = (3.3, 3.3) near the unstable point  $S_0 = (3.19, 3.19)$  - to a double picked distribution centerd on the two stable points  $S_1$  and  $S_2$ .

## Equilibrium state



Contour levels of the density  $f(\nu_1, \nu_2)$  at equilibrium. We note that there are two points of mass concentration around  $S_1 = (1.32, 5.97)$  and  $S_2 = (5.97, 1.32)$  which are the stable equilibrium points of the ODS.

#### Densities distributions



Probablity densities  $\rho_i(t)$ , i = 1, 2, 3, computed on three different domains  $\Omega_1 = [5, 10] \times [0, 2]$ ,  $\Omega_2 = [2, 5] \times [2, 5]$ ,  $\Omega_3 = [2, 5] \times [5, 10]$ . Each domain contains one of the three equilibrium points. The initial condition  $\Rightarrow \rho_1(0) = \rho_3(0) = 0$  and  $\rho_2(0) = 1$ .

## Escaping time

Let  $f(0, \nu_1, \nu_2)$  be a gaussian distribution centered in  $S_1$  and  $\beta = 0.2, ..., 1$ . Let T be the escaping time (ie. the time needed for half of the mass to pass from the neighborhood of  $S_1$  to the neighborhood of  $S_2$ ) :  $\rho_1(T) < 2\rho_3(T)$ . Then T has an exponential behaviour :

| $\beta$ | 0.2    | 0.3   | 0.4   | 0.5   | 0.6  | 0.7  | 0.8  | 0.9  | 1    |
|---------|--------|-------|-------|-------|------|------|------|------|------|
| T       | 1290.3 | 332.7 | 168.5 | 109.3 | 78.2 | 60.9 | 48.0 | 37.1 | 32.1 |



Escaping time T with respect to the diffusion coefficient  $\beta$  in log scale

# Slow-fast behaviour



One realisation of a trajectory for the ODS starting in (5,5)

The blue lines are numerical approximations of the solution of the deterministic system

$$\begin{pmatrix} \dot{\nu_1} = -\nu_1 + \phi \left(\lambda + \sum_{j=1,2} w_{1j} \nu_j \right) \\ \dot{\nu_2} = -\nu_2 + \phi \left(\lambda + \sum_{j=1,2} w_{2j} \nu_j \right) \end{cases}$$

and highlight the slow manifold to which belongs the stable and unstable solutions of this system

 $\Rightarrow$  fast to the manifold, slow on the manifold

[BG] N.Berglund, B.Gentz, Noise-Induced Phenomena in Slow-Fast Dynamical Systems. A Sample-Paths Approach. Springer, Probability and its Applications (2005)

#### Towards a one-dimensional problem

The change of variables:  $x = \nu_1 + \nu_2$ ,  $y = \nu_1 - \nu_2$  leads to the system :

$$\begin{cases} \varepsilon \dot{x} = h(x, y) \\ \dot{y} = g(x, y) \end{cases}, \qquad \varepsilon = \frac{\partial_y g}{\partial_x h}|_{S_0} \end{cases}$$

It is possible to find a function  $x^*(y)$  and to reduce the system to a onedimensional equation defined on the slow manifold :

$$\dot{y} = g(x^*(y), y)$$

Taking into account the white noise, the original FP model, reduces to a FP equation, for which the unknown distirbution function depends on time t and the y variable, and the equilibrium solution is given by an exponential function:

$$\exp\left(\frac{-G}{\beta^2}\right), \qquad G = \partial_y g(x^*(y), y)$$

# **Conclusions and Perspectives**

- We present theoretical results concerning the existence, uniqueness, positivity of the solution for the model (non-potential frame), and its convergence towards the solution of the stationnary associated problem.
- We propose a kinetic model for the evolution of two interacting populations (decision making), based on neurodynamical systems.
- Our numerical results agree with those find by G.Deco et al. applying moments methods on the ODS.
- Investigate the slow-fast behavior of the ODS and derive a one-dimensional pde for the distribution function defined along the slow-manifold.
- Study the system in the biased case  $(\lambda_1 \neq \lambda_2)$ , or including some *adaptation in rivalry* term in the sigmoidal function.
- Stochastic Models in Neuroscience, 18-22 January 2010, CIRM, Marseille (France). http://www.fdpoisson.org/colloques/neurostoch/